Domain Decomposition Methods for the Poisson-Boltzmann Equations

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Joint work with B. Stamm (Universität Stuttgart, Stuttgart)





Outline

- 1 Model Problem
- 2 ddPB Method
- 3 ddPB Derivation
- 4 Numerical Studies
- 5 Conclusions and Outlook





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• Poisson-Boltzman (PB) Equation

$$-\nabla \cdot \left[\varepsilon(\mathbf{x})\nabla \tilde{\psi}(\mathbf{x})\right] = 4\pi \left(\rho^{\mathsf{sol}}(\mathbf{x}) + \rho^{\mathsf{ions}}(\mathbf{x})\right) \quad \text{in } \mathbb{R}^3$$

 $\circ \ ilde{\psi}(\mathbf{x})$: Electrostatic potential





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• Poisson-Boltzman (PB) Equation

$$-\nabla \cdot \left[\varepsilon(\mathbf{x})\nabla \tilde{\psi}(\mathbf{x})\right] = 4\pi \left(\rho^{\mathsf{sol}}(\mathbf{x}) + \rho^{\mathsf{ions}}(\mathbf{x})\right) \quad \text{in } \mathbb{R}^3$$

 $\begin{array}{l} \circ ~~ \tilde{\psi}(\mathbf{x}) : \text{Electrostatic potential} \\ \circ ~~ \varepsilon(\mathbf{x}) : \text{Space-dependent dielectric permittivity} \\ \circ ~~ \rho^{\mathsf{sol}}(\mathbf{x}) : \text{Solute charge distribution} \end{array}$

$$\rho^{\mathsf{sol}}(\mathbf{x}) = \sum_{i=1}^{\mathsf{M}} q_i \delta(\mathbf{x} - \mathbf{x}_i)$$

- M : Number of solute atoms
- q_i : Total charge on the i^{th} atom





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$\circ \ \rho^{ions}(\mathbf{x})$: lonic charge distribution

$$\rho^{\text{ions}}(\mathbf{x}) = \sum_{i=1}^{N_{\text{ions}}} z_i e \lambda(\mathbf{x}) c_i^{\infty} \exp\left(\frac{-z_i e \tilde{\psi}(\mathbf{x})}{K_{\text{B}} T}\right)$$

¹Stein, Herbert, Head-Gordon: JCP, 151(22), 2019





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$$\rho^{\text{ions}}(\mathbf{x}) = \sum_{i=1}^{N_{\text{ions}}} z_i e \lambda(\mathbf{x}) c_i^{\infty} \exp\left(\frac{-z_i e \tilde{\psi}(\mathbf{x})}{K_{\text{B}} T}\right)$$

• For 1:1 ionic solution¹

$$ho^{
m ions}(\mathbf{x}) = -2ce\lambda(\mathbf{x})\sinh\left(rac{e ilde{\psi}(\mathbf{x})}{K_{
m B}T}
ight)$$

 $-\lambda(\mathbf{x})$: Ion-exclusion function







Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• For 1:1 solution Poisson-Boltzman (PB) Equation

$$-\nabla \cdot \left[\varepsilon(\mathbf{x})\nabla \tilde{\psi}(\mathbf{x})\right] + 8\pi e c \lambda(\mathbf{x}) \sinh\left(\frac{e\tilde{\psi}(\mathbf{x})}{K_{\mathsf{B}}T}\right) = 4\pi \rho^{\mathsf{sol}}(\mathbf{x}) \quad \text{in } \ \mathbb{R}^{3}$$





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

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• Dimensionless Poisson-Boltzman (PB) Equation

$$-\nabla \cdot [\varepsilon(\mathbf{x})\nabla\psi(\mathbf{x})] + \kappa^2 \varepsilon_s \lambda(\mathbf{x}) \sinh\left(\psi(\mathbf{x})\right) = \frac{4\pi}{\beta} \rho^{\mathsf{sol}}(\mathbf{x}) \quad \text{in } \ \mathbb{R}^3$$





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• For 1:1 solution Poisson-Boltzman (PB) Equation

$$-\nabla \cdot \left[\varepsilon(\mathbf{x})\nabla \tilde{\psi}(\mathbf{x})\right] + 8\pi e c \lambda(\mathbf{x}) \sinh\left(\frac{e\tilde{\psi}(\mathbf{x})}{K_{\mathrm{B}}T}\right) = 4\pi \rho^{\mathrm{sol}}(\mathbf{x}) \quad \text{in } \ \mathbb{R}^{3}$$

• Dimensionless Poisson-Boltzman (PB) Equation

$$-\nabla \cdot [\varepsilon(\mathbf{x})\nabla\psi(\mathbf{x})] + \kappa^2 \varepsilon_{\mathsf{s}} \lambda(\mathbf{x}) \sinh(\psi(\mathbf{x})) = \frac{4\pi}{\beta} \rho^{\mathsf{sol}}(\mathbf{x}) \quad \text{in } \ \mathbb{R}^3$$

• $\psi(\mathbf{x}) : \tilde{\psi}(\mathbf{x})\beta$ • κ : Debye Hückel Screening Constant • $\beta : e/K_{B}T$







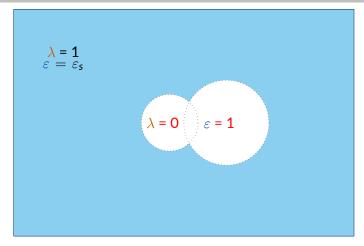


Figure 1: Solute probes and solute-solvent boundary for a molecule

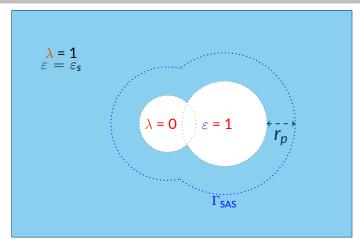


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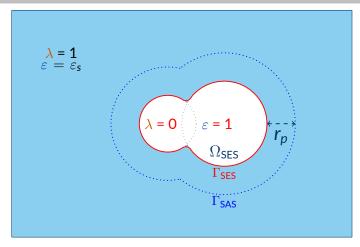


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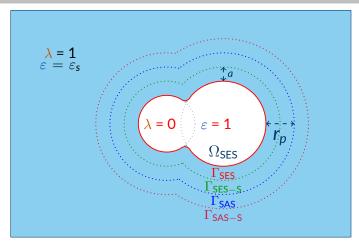


Figure 1: Solute probes and solute-solvent boundary for a molecule

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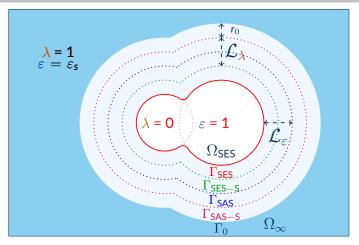


Figure 1: Solute probes and solute-solvent boundary for a molecule





Permittivity and Ion-Exclusion Function

Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

Dielectric Permittivity Function¹

$$\varepsilon(\mathbf{x}) = \begin{cases} 1 & \mathbf{x} \in \Omega_{\mathsf{SES}}, \\ 1 + (\varepsilon_{\mathsf{s}} - 1)\xi\left(\frac{\mathsf{f}_{\mathsf{SAS}-\mathsf{S}}(\mathbf{x}) + \mathsf{r}_{\mathsf{p}}}{\mathsf{r}_{0} + \mathsf{r}_{\mathsf{p}} + a}\right) & \mathbf{x} \in \mathcal{L}_{\varepsilon}, \\ \varepsilon_{\mathsf{s}} & \text{else}, \end{cases}$$

¹Quan, Stamm: JCP, 322, 760-782, 2016





Permittivity and Ion-Exclusion Function

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Dielectric Permittivity Function¹

$$\varepsilon(\mathbf{x}) = \begin{cases} 1 & \mathbf{x} \in \Omega_{\text{SES}}, \\ 1 + (\varepsilon_s - 1)\xi \left(\frac{f_{\text{SAS}-S}(\mathbf{x}) + \mathbf{r}_p}{r_0 + \mathbf{r}_p + a}\right) & \mathbf{x} \in \mathcal{L}_{\varepsilon}, \\ \varepsilon_s & \text{else}, \end{cases}$$

Ion-Exclusion Function

$$\lambda(\mathbf{x}) = \begin{cases} 0 & \mathbf{x} \in \Omega_{\mathsf{SES}-\mathsf{S}}, \\ \xi\left(\frac{\mathsf{f}_{\mathsf{SAS}-\mathsf{S}}(\mathbf{x}) + \mathbf{r}_p}{r_0 + \mathbf{r}_p + a}\right) & \mathbf{x} \in \mathcal{L}_\lambda, \\ 1 & \text{else}, \end{cases}$$

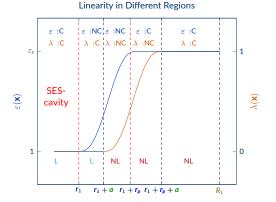
¹Quan, Stamm: JCP, 322, 760-782, 2016





Permittivity and Ion-Exclusion Function

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• $R_1: r_1 + r_p + a + r_0$

- C: Constant, NC: Non-Constant
- L: Linear, NL: Non-Linear





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• The PB equation can be written in two equations

$$\begin{split} -\nabla \cdot \left[\varepsilon(\mathbf{x}) \nabla \psi(\mathbf{x}) \right] + \kappa^2 \varepsilon_{\mathsf{s}} \lambda(\mathbf{x}) \sinh\left(\psi(\mathbf{x})\right) &= \frac{4\pi}{\beta} \rho^{\mathsf{sol}}(\mathbf{x}) \qquad \text{in } \Omega_0, \\ -\Delta \psi(\mathbf{x}) + \kappa^2 \psi(\mathbf{x}) &= 0 \qquad \qquad \text{in } \Omega_\infty, \end{split}$$

with

$$\begin{bmatrix} \boldsymbol{\psi} \end{bmatrix} = 0, \\ \begin{bmatrix} \partial_{\mathbf{n}} \boldsymbol{\psi} \end{bmatrix} = 0 \quad \text{on} \quad \Gamma_0 := \partial \Omega_0,$$





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• Using Potential Theory the final equations are

$$\begin{aligned} -\nabla \cdot \left[\varepsilon(\mathbf{x}) \nabla \psi_{\mathbf{r}}(\mathbf{x}) \right] + \kappa^2 \varepsilon_{\mathbf{s}} \lambda(\mathbf{x}) \mathcal{F} \left(\psi_{\mathbf{r}} + \psi_0 \right) \left(\psi_{\mathbf{r}} + \psi_0 \right) \left(\mathbf{x} \right) \\ = \nabla \cdot \left[\left(\varepsilon(\mathbf{x}) - 1 \right) \nabla \psi_0(\mathbf{x}) \right] & \text{in } \Omega_0 \quad [\mathsf{GSP}] \end{aligned}$$





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• Using Potential Theory the final equations are

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$$-\Delta\psi_{\mathsf{e}}(\mathbf{x}) + \kappa^{2}\psi_{\mathsf{e}}(\mathbf{x}) = 0 \quad \text{in } \Omega_{0} \quad [\mathsf{HSP}]$$





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with

$$\begin{split} \psi_0 + \psi_{\mathbf{r}} &= \psi_{\mathbf{e}} \quad \text{on } \Gamma, \\ \psi_{\mathbf{e}} &= \mathbf{S}_{\kappa} \sigma_{\mathbf{e}} \qquad \text{on } \Gamma \end{split}$$





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Using Potential Theory the final equations are

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where

- $\psi_{\mathbf{r}}$: Reaction potential in Ω
- ψ_0 : Potential generated by ρ_M satisfying,

$$-\Delta\psi_0 = \frac{4\pi}{\beta}\rho_{\mathsf{M}}$$





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

$\circ \ \psi_{\mathsf{e}}$: Extended potential from Ω^{C} to Ω^{0}

¹Sauter, Schwab, Springer, Berlin-2011, 101-181





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

 $\circ \ \psi_{\mathsf{e}} : \mathsf{Extended potential from } \Omega^{\mathsf{C}} \text{ to } \Omega^{0} \\ \circ \ \mathcal{F}(\Phi) = \frac{\mathsf{sinh}(\Phi)}{\Phi}$

¹Sauter, Schwab, Springer, Berlin-2011, 101-181





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$$\mathbf{S}_{\kappa}\sigma_{\mathbf{e}}(\mathbf{x}) = \int_{\Gamma} \frac{\exp\left(-\kappa |\mathbf{x} - \mathbf{y}|\right)\sigma_{\mathbf{e}}(\mathbf{y})}{4\pi |\mathbf{x} - \mathbf{y}|} = \psi_{\mathbf{e}} \quad \forall \ \mathbf{x} \in \Gamma$$

 $\circ~S_{\kappa}$: Invertible single-layer potential operator ^1

 $\mathbf{S}_{\boldsymbol{\kappa}}: \mathbf{H}^{-1/2}(\Gamma) \to \mathbf{H}^{1/2}(\Gamma)$

¹Sauter, Schwab, Springer, Berlin-2011, 101-181



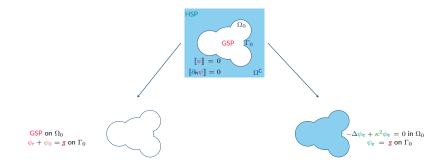








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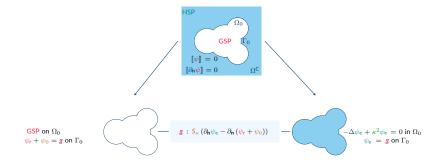








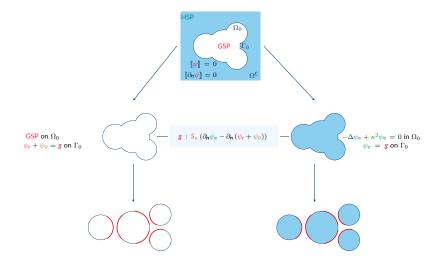
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• GSP equation in unit ball

$$\begin{split} -\nabla \cdot \left[\varepsilon (\tilde{\mathbf{x}}) \nabla u(\mathbf{x}) \right] + \lambda(\mathbf{x}) \tilde{\mathcal{F}} \left(\overline{u(\mathbf{x})} \right) u(\mathbf{x}) &= f(\mathbf{x}) \quad \text{in } B_1(\mathbf{0}) \\ u(\mathbf{x}) &= \phi_r(\mathbf{x}) \quad \text{on } \partial B_1(\mathbf{0}) \end{split}$$





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• GSP equation in unit ball

$$\begin{aligned} -\nabla \cdot \left[\tilde{\varepsilon(\mathbf{x})} \nabla u(\mathbf{x}) \right] + \lambda(\mathbf{x}) \tilde{\mathcal{F}} \left(\overline{u(\mathbf{x})} \right) u(\mathbf{x}) &= f(\mathbf{x}) \quad \text{in } B_1(\mathbf{0}) \\ u(\mathbf{x}) &= \phi_{\mathsf{r}}(\mathbf{x}) \quad \text{on } \partial B_1(\mathbf{0}) \end{aligned}$$

$$-\nabla \cdot \left[\varepsilon(\mathbf{\tilde{x}})\nabla \mathbf{w}(\mathbf{x})\right] + \lambda(\mathbf{x})\tilde{\mathcal{F}}\left(\left(\overline{\mathbf{w}+\hat{u}_{1}}\right)(\mathbf{x})\right)\mathbf{w}(\mathbf{x}) = \tilde{f}(\mathbf{x}), \quad \text{in } B_{1}(\mathbf{0})$$
$$\mathbf{w}(\mathbf{x}) = 0 \quad \text{on } \partial B_{1}(\mathbf{0})$$





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$$\circ \mathbf{w}(\mathbf{x}) = \mathbf{u}(\mathbf{x}) - \hat{u}_1(\mathbf{x})$$

$$\circ \tilde{\mathbf{f}}(\mathbf{x}) = \mathbf{f}(\mathbf{x}) + \nabla \cdot [\tilde{\varepsilon}(\mathbf{x})\nabla \hat{u}_1(\mathbf{x})] - \lambda(\mathbf{x})\tilde{\mathcal{F}}\left(\left(\overline{\mathbf{w} + \hat{u}_1}\right)(\mathbf{x})\right)\hat{u}_1(\mathbf{x})$$





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$$\mathbf{w}(\mathbf{x}) = 0 \quad \text{on } \partial B_1(\mathbf{0}),$$

- $\circ \mathbf{w}(\mathbf{x}) = \mathbf{u}(\mathbf{x}) \hat{u}_1(\mathbf{x}) \\ \circ \tilde{\mathbf{f}}(\mathbf{x}) = \mathbf{f}(\mathbf{x}) + \nabla \cdot [\tilde{\varepsilon}(\mathbf{x})\nabla \hat{u}_1(\mathbf{x})] \lambda(\mathbf{x})\tilde{\mathcal{F}}\left(\left(\overline{\mathbf{w} + \hat{u}_1}\right)(\mathbf{x})\right) \hat{u}_1(\mathbf{x})$
- $\hat{u}_1(\mathbf{x})$: Laplace solution satisfying the boundary condition





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• GSP equation in unit ball

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• Transformation to Homogeneous Problem

$$\begin{aligned} -\nabla \cdot \left[\varepsilon(\tilde{\mathbf{x}}) \nabla \mathbf{w}(\mathbf{x}) \right] + \lambda(\mathbf{x}) \tilde{\mathcal{F}} \left(\left(\overline{\mathbf{w} + \hat{u}_1} \right) (\mathbf{x}) \right) \mathbf{w}(\mathbf{x}) &= \tilde{f}(\mathbf{x}), \quad \text{ in } B_1(\mathbf{0}) \\ \mathbf{w}(\mathbf{x}) &= 0 \quad \text{ on } \partial B_1(\mathbf{0}), \end{aligned}$$

• $\mathbf{w}(\mathbf{x}) = \mathbf{u}(\mathbf{x}) - \hat{u}_1(\mathbf{x})$ • $\tilde{f}(\mathbf{x}) = f(\mathbf{x}) + \nabla \cdot [\tilde{\varepsilon}(\mathbf{x})\nabla\hat{u}_1(\mathbf{x})] - \lambda(\mathbf{x})\tilde{\mathcal{F}}\left(\left(\overline{\mathbf{w} + \hat{u}_1}\right)(\mathbf{x})\right)\hat{u}_1(\mathbf{x})$ • $\hat{u}_1(\mathbf{x})$: Laplace solution satisfying the boundary condition

• $B_{\mathbf{r}_j}(\mathbf{x}_j) \subset \Omega_j$





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• GSP equation in unit ball

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• Transformation to Homogeneous Problem

$$\begin{aligned} -\nabla \cdot \left[\varepsilon(\mathbf{\tilde{x}}) \nabla \mathbf{w}(\mathbf{x}) \right] + \lambda(\mathbf{x}) \tilde{\mathcal{F}} \left(\left(\overline{\mathbf{w} + \hat{u}_1} \right) (\mathbf{x}) \right) \mathbf{w}(\mathbf{x}) &= \tilde{f}(\mathbf{x}), \quad \text{ in } B_1(\mathbf{0}) \\ \mathbf{w}(\mathbf{x}) &= 0 \quad \text{ on } \partial B_1(\mathbf{0}), \end{aligned}$$

- $\circ \mathbf{w}(\mathbf{x}) = \mathbf{u}(\mathbf{x}) \hat{u}_1(\mathbf{x}) \\ \circ \tilde{\mathbf{f}}(\mathbf{x}) = \mathbf{f}(\mathbf{x}) + \nabla \cdot [\tilde{\varepsilon}(\mathbf{x})\nabla \hat{u}_1(\mathbf{x})] \lambda(\mathbf{x})\tilde{\mathcal{F}}\left(\left(\overline{\mathbf{w} + \hat{u}_1}\right)(\mathbf{x})\right) \hat{u}_1(\mathbf{x})$
- $\hat{u}_1(\mathbf{x})$: Laplace solution satisfying the boundary condition

•
$$B_{r_j}(\mathbf{x}_j) \subset \Omega_j$$

• $\psi_{\mathbf{r}}(\mathbf{x})$ is harmonic in $B_{\mathbf{r}_j}(\mathbf{x}_j)$





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• GSP equation in unit ball

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- $\circ \mathbf{w}(\mathbf{x}) = \mathbf{u}(\mathbf{x}) \hat{u}_1(\mathbf{x})$ $\circ \tilde{f}(\mathbf{x}) = f(\mathbf{x}) + \nabla \cdot [\tilde{\varepsilon}(\mathbf{x})\nabla \hat{u}_1(\mathbf{x})] - \lambda(\mathbf{x})\tilde{\mathcal{F}}\left(\left(\overline{\mathbf{w} + \hat{u}_1}\right)(\mathbf{x})\right)\hat{u}_1(\mathbf{x})$
- $\hat{u}_1(\mathbf{x})$: Laplace solution satisfying the boundary condition
- $B_{\mathbf{r}_j}(\mathbf{x}_j) \subset \Omega_j$
 - $\psi_{\mathbf{r}}(\mathbf{x})$ is harmonic in $B_{\mathbf{r}_i}(\mathbf{x}_j)$
 - $\mathbf{w}(\mathbf{x})$ is harmonic in $B_{\delta}(\mathbf{0})$ where

$$\delta = \frac{\mathbf{r}_j}{\mathbf{r}_j + \mathbf{r}_0 + \mathbf{r}_p + a} \in (0, 1)$$





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• Find $\mathbf{w} \in H^1_{0,\delta}(\mathcal{D})$ such that

$$\begin{split} \int_{\mathcal{D}} \tilde{\varepsilon}(\mathbf{x}) \nabla w(\mathbf{x}) \nabla \tilde{w}(\mathbf{x}) &+ \int_{\mathcal{D}} \lambda(\mathbf{x}) \tilde{\mathcal{F}}\left(\overline{w}(\mathbf{x})\right) w(\mathbf{x}) \tilde{w}(\mathbf{x}) \\ &+ \int_{\partial \mathsf{B}_{\delta}(\mathbf{0})} \left(\mathcal{T} w\right) \tilde{w}(\mathbf{x}) = \int_{\mathcal{D}} \tilde{f}(\mathbf{x}) \tilde{w}(\mathbf{x}) \quad \forall \ \tilde{w} \in H^{1}_{0,\delta}(\mathcal{D}), \end{split}$$





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$$\begin{split} \int_{\mathcal{D}} \tilde{\varepsilon}(\mathbf{x}) \nabla \mathbf{w}(\mathbf{x}) \nabla \tilde{w}(\mathbf{x}) &+ \int_{\mathcal{D}} \lambda(\mathbf{x}) \tilde{\mathcal{F}}\left(\overline{\mathbf{w}}(\mathbf{x})\right) \mathbf{w}(\mathbf{x}) \tilde{w}(\mathbf{x}) \\ &+ \int_{\partial B_{\delta}(\mathbf{0})} \left(\mathcal{T}\mathbf{w}\right) \tilde{w}(\mathbf{x}) = \int_{\mathcal{D}} \tilde{\mathbf{f}}(\mathbf{x}) \tilde{w}(\mathbf{x}) \quad \forall \ \tilde{w} \in H^{1}_{0,\delta}(\mathcal{D}), \end{split}$$

$$\circ \ \mathcal{D} = \mathsf{B}_1(\mathbf{0}) \setminus \mathsf{B}_{\delta}(\mathbf{0}) \\ \circ \ \mathsf{H}_{0,\delta}^1(\mathcal{D}) = \left\{ \mathsf{w} \in \mathsf{H}^1(\mathcal{D}) : \mathsf{w}|_{\partial \mathsf{B}_1(\mathbf{0})} = 0 \right\}$$





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• Find $\mathbf{w} \in H^1_{0,\delta}(\mathcal{D})$ such that

$$\begin{split} \int_{\mathcal{D}} \tilde{\varepsilon}(\mathbf{x}) \nabla \mathbf{w}(\mathbf{x}) \nabla \tilde{w}(\mathbf{x}) &+ \int_{\mathcal{D}} \lambda(\mathbf{x}) \tilde{\mathcal{F}}\left(\overline{\mathbf{w}}(\mathbf{x})\right) \mathbf{w}(\mathbf{x}) \tilde{w}(\mathbf{x}) \\ &+ \int_{\partial \mathcal{B}_{\delta}(\mathbf{0})} \left(\mathcal{T}\mathbf{w}\right) \tilde{w}(\mathbf{x}) = \int_{\mathcal{D}} \tilde{\mathbf{f}}(\mathbf{x}) \tilde{w}(\mathbf{x}) \quad \forall \ \tilde{w} \in H^{1}_{0,\delta}(\mathcal{D}), \end{split}$$

$$\circ \ \begin{array}{l} \mathcal{D} = \mathcal{B}_1(\mathbf{0}) \setminus \mathcal{B}_{\delta}(\mathbf{0}) \\ \circ \ \mathcal{H}_{0,\delta}^1(\mathcal{D}) = \left\{ \mathbf{w} \in \mathcal{H}^1(\mathcal{D}) : \mathbf{w}|_{\partial \mathcal{B}_1(\mathbf{0})} = 0 \right\} \end{array}$$

Using Galerkin discretisation

 $\mathsf{w}(\mathbf{r},\theta,\varphi) = \sum_{i=0}^{N} \sum_{\ell=0}^{\ell_{\max}} \sum_{m=-\ell}^{\ell} [\phi_{\mathbf{r}}]_{i\ell}^{m} \underline{\varrho_{i}}(\mathbf{r}) Y_{\ell}^{m}(\theta,\varphi) \quad \forall \ \delta \leq \mathbf{r} \leq 1; \quad 0 \leq \theta \leq \pi; \quad 0 \leq \varphi \leq 2\pi,$

- ϱ_i : Legendre polynomial of order *i*
- N : Maximum degree of Legendre polynomial of order ϱ_i
- Y_{ℓ}^m : Spherical Harmonic Basis
- ℓ_{max} : Maximum degree of Y_{ℓ}^{m}





• System of Equation

$$\mathbf{AX}_{\mathbf{r}} = \mathbf{F}$$

where

• $k(:= N(\ell^2 + m + 1) + i \in \{1, 2, ..., N(\ell_{max} + 1)^2\}), k' \text{ entry}$

$$\begin{split} [\mathbf{A}]_{\mathbf{k},\mathbf{k}'} &= \int_{\mathcal{D}} \tilde{\varepsilon}(\mathbf{x}) \nabla \left(\varrho_{i} \mathbf{Y}_{\ell}^{m} \right) \cdot \nabla \left(\varrho_{j} \mathbf{Y}_{\ell'}^{m'} \right) \\ &+ \int_{\mathcal{D}} \lambda(\mathbf{x}) \tilde{\mathcal{F}} \left(\overline{\tilde{\mathbf{w}}}(\mathbf{x}) \right) \varrho_{i} \mathbf{Y}_{\ell}^{m} \varrho_{j} \mathbf{Y}_{\ell'}^{m} \\ &+ \frac{\ell}{\delta} \int_{\partial \mathbf{B}_{\delta}(\mathbf{0})} \varrho_{i} \mathbf{Y}_{\ell}^{m} \varrho_{j} \mathbf{Y}_{\ell'}^{m'}, \end{split}$$

$$[\mathbf{F}]_{\mathbf{k}} = \int_{\mathcal{D}} \tilde{f}_{\boldsymbol{\varrho}_{\mathbf{j}}} \mathbf{Y}_{\ell'}^{\mathbf{m}'} \quad \forall \ \mathbf{k} \in \{1, \dots, \mathsf{N}(\ell_{\max} + 1)^2\}.$$





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• HSP equation in unit ball ¹

$$\begin{aligned} -\Delta u_{\mathsf{e}} + \kappa^2 u_{\mathsf{e}}^2 &= 0 \quad \text{ in } \mathcal{B}_1(0), \\ u_{\mathsf{e}} &= \phi_{\mathsf{e}} \quad \text{ on } \mathbb{S}^2 \end{aligned}$$

• $u_{\rm e}$ can be numerically approximated by $\tilde{u}_{\rm e}$

$$\tilde{\mathsf{u}}_{\mathsf{e}}(\mathbf{r},\theta,\varphi) = \sum_{\ell=0}^{\ell_{\max}} \sum_{\mathbf{m}=-\ell}^{\ell} \left[\tilde{\phi}_{\mathsf{e}} \right]_{\ell}^{\mathbf{m}} \frac{\mathbf{i}_{\ell}(\mathbf{r})}{\mathbf{i}_{\ell}(1)} \mathbf{Y}_{\ell}^{\mathbf{m}}(\theta,\varphi)$$
for $0 \le \mathbf{r} \le 1, \ 0 \le \theta \le \pi, \ 0 \le \varphi < 2\pi$

¹Quan, Stamm, Maday: SISC, 41(2), B320-B350, 2019





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for $0 \leq \mathbf{r} \leq 1, \ 0 \leq \theta \leq \pi, \ 0 \leq \varphi < 2\pi$ $\circ \ \left[\tilde{\phi}_{\mathsf{e}} \right]_{\ell}^{\mathsf{m}}$: Numerical approximation of $\left[\phi_{\mathsf{e}} \right]_{\ell}^{\mathsf{m}}$

$$\left[\tilde{\phi}_{\mathsf{e}}\right]_{\ell}^{\mathsf{m}} = \sum_{n=1}^{\mathsf{N}_{\mathsf{leb}}} \omega_{\mathsf{n}}^{\mathsf{leb}} \phi_{\mathsf{e}}(s_{\mathsf{n}}) \mathbf{Y}_{\ell}^{\mathsf{m}}(s_{\mathsf{n}})$$

¹Quan, Stamm, Maday: SISC, 41(2), B320-B350, 2019



Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• Numerical Integration¹²

¹ Haxton: J.Phy.B, 40, 4443, 2007 ² Parter: JSC, 14, 347-355, 1999



Abhinav Jha ddPB method, 2nd June 2023



Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• Numerical Integration¹²

$$\begin{split} \int_{\mathcal{D}} h(\mathbf{x}) d\mathbf{x} &= \int_{\delta}^{1} r^{2} \int_{\mathbb{S}^{2}} h(r, \mathbf{s}) d\mathbf{s} dr \\ &\approx \frac{1 - \delta}{2} \sum_{m=1}^{N_{\text{lgl}}} \sum_{n=1}^{N_{\text{leb}}} \omega_{m}^{\text{lgl}} \omega_{n}^{\text{leb}} \left(\frac{1 - \delta}{2} (\mathbf{x}_{m} + 1) + \delta \right)^{2} \\ &\times h \left(\frac{1 - \delta}{2} (\mathbf{x}_{m} + 1) + \delta, \mathbf{s}_{n} \right). \end{split}$$

¹Haxton: J.Phy.B, 40, 4443, 2007 ²Parter: JSC, 14, 347-355, 1999





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• Energy Computation¹

$$\mathsf{E}_{\mathsf{s}} = \frac{1}{2} \int_{\mathbb{R}} \left(\rho^{\mathsf{sol}}(\mathbf{x}) \psi_{\mathsf{r}}(\mathbf{x}) - \rho^{\mathsf{ions}}(\mathbf{x}) \psi_{\mathsf{r}}(\mathbf{x}) - 2\Delta \Pi \right) d\mathbf{x}$$

 $\circ \Delta \Pi$: Osmotic Pressure





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• Energy Computation¹

$$\mathsf{E}_{\mathsf{s}} = \frac{1}{2} \int_{\mathbb{R}} \left(\rho^{\mathsf{sol}}(\mathbf{x}) \psi_{\mathsf{r}}(\mathbf{x}) - \rho^{\mathsf{ions}}(\mathbf{x}) \psi_{\mathsf{r}}(\mathbf{x}) - 2\Delta \Pi \right) d\mathbf{x}$$

- $\circ \ \ \Delta \Pi : Osmotic \ Pressure$
- Stopping Criteria
 - Global Iterative Process

$$|E_s^{k} - E_s^{k-1}|/|E_s^{k}| \leq \mathsf{tol}$$





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• Energy Computation¹

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 - Global Iterative Process

$$|E_s^k - E_s^{k-1}| / |E_s^k| \le \mathsf{tol}$$

• DD loop

$$\frac{\|\mathbf{X}_{\mathsf{r}}^{\mathsf{k}} - \mathbf{X}_{\mathsf{r}}^{\mathsf{k}-1}\|_{\ell^2}}{\|\mathbf{X}_{\mathsf{r}}^{\mathsf{k}}\|_{\ell^2}} \le 10 \times \mathsf{tol}$$





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• Energy Computation¹

$$\mathsf{E}_{\mathsf{s}} = \frac{1}{2} \int_{\mathbb{R}} \left(\rho^{\mathsf{sol}}(\mathbf{x}) \psi_{\mathsf{r}}(\mathbf{x}) - \rho^{\mathsf{ions}}(\mathbf{x}) \psi_{\mathsf{r}}(\mathbf{x}) - 2\Delta \Pi \right) d\mathbf{x}$$

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$$\frac{\|\boldsymbol{\mathsf{X}}_{\mathsf{r}}^{\mathsf{k}} - \boldsymbol{\mathsf{X}}_{\mathsf{r}}^{\mathsf{k}-1}\|_{\ell^2}}{\|\boldsymbol{\mathsf{X}}_{\mathsf{r}}^{\mathsf{k}}\|_{\ell^2}} \le 10 \times \mathsf{tol}$$

• Matrix loop

$$\frac{\|\mathbf{X}_{\mathsf{r},\mathsf{i}}^{\mathsf{k}} - \mathbf{X}_{\mathsf{r},\mathsf{i}}^{\mathsf{k}-1}\|_{\ell^2}}{\|\mathbf{X}_{\mathsf{r},\mathsf{i}}^{\mathsf{k}}\|_{\ell^2}} \le 100 \times \mathsf{tol}$$





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• Constants in the model





• Constants in the model

- ε_s: 78.54
- κ: 0.104 Å^{−1}
- T: 298.15 K
- $\circ\,$ tol: 10^{-7}





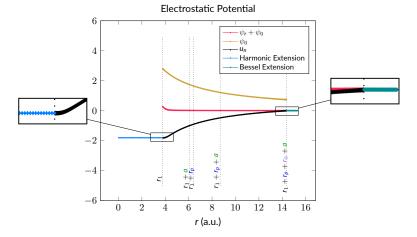
• Constants in the model

- ε_s: 78.54
- κ: 0.104 Å^{−1}
- T: 298.15 K
- tol: 10^{-7}
- Conversion to atomic units





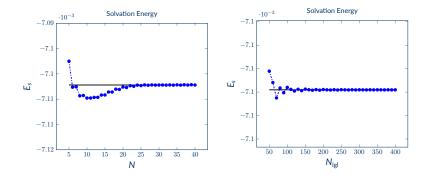
- Discretisation Parameters: N = 20, $N_{\text{lgl}} = 300$
- Geometric Parameters: $r_1 = 2$ Å, $r_0 = 3$ Å, $r_p = 1.4$ Å, a = 1.2 Å







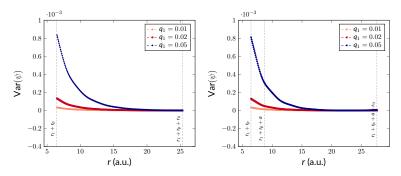
- Discretisation Parameters: N = 40, $N_{|g|} = 400$
- Geometric Parameters: $r_1 = 2$ Å, $r_0 = 10$ Å, $r_p = 1.4$ Å, a = 1.2 Å







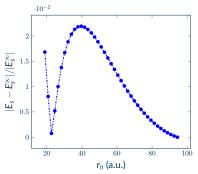
- Discretisation Parameters: N = 20, $N_{lgl} = 200$
- Geometric Parameters: $r_1 = 2 \text{ Å}$, $r_0 = 10 \text{ Å}$, $r_p = 1.4 \text{ Å}$, a = 0 Å (left) , and a = 1.2 Å (right)



• Var(
$$\psi$$
)=|sinh(ψ)/ ψ - 1|



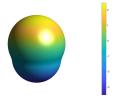
- Discretisation Parameters: N = 20, $N_{lgl} = 500$
- Geometric Parameters: $r_1 = 2$ Å, $r_0 = 50$ Å, $r_p = 1.4$ Å, a = 1.2 Å







- Discretisation Parameters: N = 15, $N_{lgl} = 50$, $\ell_{max} = 11$, $N_{leb} = 1202$
- Geometric Parameters: Hydrogen Fluoride Molecule, $r_0 = 30$ Å, $r_p = 1.4$ Å, a = 1.2 Å







Conclusions and Outlook

Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• Conclusions

• Formulation of domain decomposition method for PB equations

¹Herbst, J., Lipparini, Mikhalev, Notolli, Stamm, ddX: https://github.com/ddsolvation/ddX





- Conclusions
 - Formulation of domain decomposition method for PB equations
 - Development of a non-linear solver

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- Conclusions
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Thank You!

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