

A Residual based a Posteriori Error Estimators for Algebraic Flux Correction Scheme

Abhinav Jha

Applied and Computational Mathematics, RWTH Aachen University

Chemnitz Finite Element Symposium 2021
7th September 2021

1 Algebraic Flux Correction Schemes

2 A Posteriori Error Analysis

2.1 Residual Based Approach

2.2 AFC-SUPG Approach

2.3 Numerical Studies

3 Conclusions and Outlook

- Steady-state convection-diffusion-reaction equation

$$\begin{aligned} -\varepsilon \Delta u + \mathbf{b} \cdot \nabla u + cu &= f && \text{in } \Omega \\ u &= u_b && \text{on } \Gamma_D, \\ -\varepsilon \nabla u \cdot \mathbf{n} &= g && \text{on } \Gamma_N \end{aligned} \tag{1}$$

- Ω – bounded polyhedral Lipschitz domain in \mathbb{R}^d , $d \in \{2, 3\}$
- \mathbf{n} – outward pointing unit normal
- Assume

$$\left(c(x) - \frac{1}{2} \nabla \cdot \mathbf{b}(x) \right) \geq \sigma > 0$$

- Interested in convection-dominated regime, $\varepsilon \ll \|\mathbf{b}\|_{L^\infty(\Omega)} L$
- L – Characteristic length of the problem

- Ideal discretization
 1. Accurate and sharp layers
 - Many discretizations satisfy this property, e.g., SUPG
 - Reasonably well for AFC schemes

¹J.,John: CAMWA (78), 3117-3138, 2019

- Ideal discretization
 1. Accurate and sharp layers
 - Many discretizations satisfy this property, e.g., SUPG
 - Reasonably well for AFC schemes
 2. Physically consistent results (no spurious oscillations)
 - Most discretizations violate this property, e.g., SUPG, SOLD schemes
 - Satisfied for AFC schemes

¹J.,John: CAMWA (78), 3117-3138, 2019

- Ideal discretization
 1. Accurate and sharp layers
 - Many discretizations satisfy this property, e.g., SUPG
 - Reasonably well for AFC schemes
 2. Physically consistent results (no spurious oscillations)
 - Most discretizations violate this property, e.g., SUPG, SOLD schemes
 - Satisfied for AFC schemes
 3. Efficient computation of the solutions
 - Satisfied for linear discretizations
 - Usually not satisfied for nonlinear discretizations, like AFC schemes ¹

¹J.,John: CAMWA (78), 3117-3138, 2019

- Ideal discretization
 1. Accurate and sharp layers
 - Many discretizations satisfy this property, e.g., SUPG
 - Reasonably well for AFC schemes
 2. Physically consistent results (no spurious oscillations)
 - Most discretizations violate this property, e.g., SUPG, SOLD schemes
 - Satisfied for AFC schemes
 3. Efficient computation of the solutions
 - Satisfied for linear discretizations
 - Usually not satisfied for nonlinear discretizations, like AFC schemes ¹
- Because of 2nd property: AFC schemes very well suited for applications

¹J.,John: CAMWA (78), 3117-3138, 2019

- **Variational problem** for AFC scheme

Find $u_h \in V_h$ such that

$$a_h(u_h, v_h) + d_h(u_h; u_h, v_h) = \langle f, v_h \rangle \quad \forall v_h \in V_h$$

- V_h – finite element space with homogeneous Dirichlet boundary conditions ($V_h \subset V$)
- stabilization

$$d_h(w; z, v) = \sum_{i,j=1}^N (1 - \alpha_{ij}(w)) d_{ij}(z_j - z_i) v_i \quad \forall w, v, z \in V_h$$

¹Barrenechea, John, Knobloch, Rankin: SeMA Journal (75), 655–685, 2018

- **Variational problem** for AFC scheme

Find $u_h \in V_h$ such that

$$a_h(u_h, v_h) + d_h(u_h; u_h, v_h) = \langle f, v_h \rangle \quad \forall v_h \in V_h$$

- V_h – finite element space with homogeneous Dirichlet boundary conditions ($V_h \subset V$)
- stabilization

$$d_h(w; z, v) = \sum_{i,j=1}^N (1 - \alpha_{ij}(w)) d_{ij}(z_j - z_i) v_i \quad \forall w, v, z \in V_h$$

- Another representation of stabilization for $w, v, z \in V_h$,¹

$$d_h(w; z, v) = \sum_{E \in \mathcal{E}_h} (1 - \alpha_E(w)) d_E h_E (\nabla z \cdot \mathbf{t}_E, \nabla v \cdot \mathbf{t}_E)$$

¹Barrenechea, John, Knobloch, Rankin: SeMA Journal (75), 655–685, 2018

- AFC norm

$$\|u_h\|_{\text{AFC}}^2 = \|u_h\|_a^2 + d_h(u_h, u_h, u_h) \quad \forall u_h \in V_h$$

- where $\|u_h\|_a^2 = \varepsilon |u_h|_1^2 + \sigma \|u_h\|_0^2$

¹John, Novo: CMAME (255), 289–305, 2013

- AFC norm

$$\|u_h\|_{\text{AFC}}^2 = \|u_h\|_a^2 + d_h(u_h, u_h, u_h) \quad \forall u_h \in V_h$$

- where $\|u_h\|_a^2 = \varepsilon |u_h|_1^2 + \sigma \|u_h\|_0^2$
- Let $I_h u$ denote the Scott-Zhang interpolation operator. Galerkin orthogonality arguments

$$\begin{aligned} \|u - u_h\|_{\text{AFC}}^2 &= \langle f, u - I_h u \rangle + \langle g, u - I_h u \rangle_{\Gamma_N} - a_h(u_h, u - I_h u) \\ &\quad + d_h(u_h; u, I_h u - u_h) \end{aligned}$$

¹ John, Novo: CMAME (255), 289-305, 2013

- AFC norm

$$\|u_h\|_{\text{AFC}}^2 = \|u_h\|_a^2 + d_h(u_h, u_h, u_h) \quad \forall u_h \in V_h$$

- where $\|u_h\|_a^2 = \varepsilon |u_h|_1^2 + \sigma \|u_h\|_0^2$
- Let $I_h u$ denote the Scott-Zhang interpolation operator. Galerkin orthogonality arguments

$$\|u - u_h\|_{\text{AFC}}^2 = \langle f, u - I_h u \rangle + \langle g, u - I_h u \rangle_{\Gamma_N} - a_h(u_h, u - I_h u) + d_h(u_h; u, I_h u - u_h)$$

- Standard residual a posteriori error bound ¹

$$\begin{aligned} & \langle f, u - I_h u \rangle + \langle g, u - I_h u \rangle_{\Gamma_N} - a_h(u_h, u - I_h u) \\ &= \sum_{K \in \mathcal{T}_h} (R_K(u_h), u - I_h u)_K + \sum_{F \in \mathcal{F}_h} \langle R_F(u_h), u - I_h u \rangle_F \end{aligned}$$

¹ John, Novo: CMAME (255), 289-305, 2013

with

$$\begin{aligned} R_K(u_h) &:= f + \varepsilon \Delta u_h - \mathbf{b} \cdot \nabla u_h - \mathbf{c} u_h|_K, \\ R_F(u_h) &:= \begin{cases} -\varepsilon [|\nabla u_h \cdot \mathbf{n}_F|]_F & \text{if } F \in \mathcal{F}_{h,\Omega}, \\ g - \varepsilon (\nabla u_h \cdot \mathbf{n}_F) & \text{if } F \in \mathcal{F}_{h,N}, \\ 0 & \text{if } F \in \mathcal{F}_{h,D} \end{cases} \end{aligned}$$

with

$$R_K(u_h) := f + \varepsilon \Delta u_h - \mathbf{b} \cdot \nabla u_h - \mathbf{c} u_h|_K,$$
$$R_F(u_h) := \begin{cases} -\varepsilon [|\nabla u_h \cdot \mathbf{n}_F|]_F & \text{if } F \in \mathcal{F}_{h,\Omega}, \\ g - \varepsilon (\nabla u_h \cdot \mathbf{n}_F) & \text{if } F \in \mathcal{F}_{h,N}, \\ 0 & \text{if } F \in \mathcal{F}_{h,D} \end{cases}$$

- Using interpolation estimates, Cauchy-Schwarz, and Young's inequality

$$\begin{aligned} & \|u - u_h\|_a^2 + \frac{C_Y}{C_Y - 1} d_h(u_h; u - u_h, u - u_h) \\ & \leq \frac{C_Y^2}{2(C_Y - 1)} \sum_{K \in \mathcal{T}_h} \min \left\{ \frac{C_I^2}{\sigma}, \frac{C_I^2 h_K^2}{\varepsilon} \right\} \|R_K(u_h)\|_{L^2(K)}^2 \\ & \quad + \frac{C_Y^2}{2(C_Y - 1)} \sum_{F \in \mathcal{F}_h} \min \left\{ \frac{C_F^2 h_F}{\varepsilon}, \frac{C_F^2}{\sigma^{1/2} \varepsilon^{1/2}} \right\} \|R_F(u_h)\|_{L^2(F)}^2 \\ & \quad + \frac{C_Y}{C_Y - 1} d_h(u_h; u, I_h u - u_h) \end{aligned}$$

- Linearity of $d_h(\cdot; \cdot, \cdot)$,

$$d_h(u_h; u, l_h u - u_h) = d_h(u_h; u - u_h, l_h u - u_h) + d_h(u_h; u_h, l_h u - u_h)$$

- Linearity of $d_h(\cdot; \cdot, \cdot)$,

$$d_h(u_h; u, l_h u - u_h) = d_h(u_h; u - u_h, l_h u - u_h) + d_h(u_h; u_h, l_h u - u_h)$$

- Using interpolation estimates, Cauchy-Schwarz, trace inequality, inverse estimate, and Young's inequality

$$\begin{aligned} d_h(u_h; u_h, l_h u - u_h) &\leq \frac{C_Y}{2} \sum_{E \in \mathcal{E}_h} \min \left\{ \frac{\kappa_1 h_E^2}{\varepsilon}, \frac{\kappa_2}{\sigma} \right\} (1 - \alpha_E)^2 |d_E|^2 h_E^{1-d} \\ &\quad \times \|\nabla u_h \cdot \mathbf{t}_E\|_{L^2(E)}^2 + \frac{1}{C_Y} \|u - u_h\|_a^2, \end{aligned}$$

where

$$\begin{aligned} \kappa_1 &= C_{\text{edge,max}} (1 + (1 + C_I)^2), \\ \kappa_2 &= C_{\text{inv}}^2 C_{\text{edge,max}} (1 + (1 + C_I)^2). \end{aligned}$$

Theorem (Global a posteriori error estimate)

A global a posteriori error estimate for the energy norm is given by

$$\|u - u_h\|_a^2 \leq \eta_1^2 + \eta_2^2 + \eta_3^2,$$

where

$$\eta_1^2 = \sum_{K \in \mathcal{T}_h} \min \left\{ \frac{4C_I^2}{\sigma}, \frac{4C_I^2 h_K^2}{\varepsilon} \right\} \|R_K(u_h)\|_{L^2(K)}^2,$$

$$\eta_2^2 = \sum_{F \in \mathcal{F}_h} \min \left\{ \frac{4C_F^2 h_F}{\varepsilon}, \frac{4C_F^2}{\sigma^{1/2} \varepsilon^{1/2}} \right\} \|R_F(u_h)\|_{L^2(F)}^2,$$

$$\eta_3^2 = \sum_{E \in \mathcal{E}_h} \min \left\{ \frac{4\kappa_1 h_E^2}{\varepsilon}, \frac{4\kappa_2}{\sigma} \right\} (1 - \alpha_E)^2 |d_E|^2 h_E^{1-d} \|\nabla u_h \cdot \mathbf{t}_E\|_{L^2(E)}^2$$

- Formal local lower bound for a mesh cell K

$$\eta_K^2 = \eta_{\text{Int},K}^2 + \sum_{F \in \mathcal{F}_h(K)} \eta_{\text{Face},F}^2 + \sum_{E \in \mathcal{E}_h(K)} \eta_{d_h,E}^2$$

- Formal local lower bound for a mesh cell K

$$\eta_K^2 = \eta_{\text{Int},K}^2 + \sum_{F \in \mathcal{F}_h(K)} \eta_{\text{Face},F}^2 + \sum_{E \in \mathcal{E}_h(K)} \eta_{d_h,E}^2$$

where

$$\begin{aligned}\eta_{\text{Int},K}^2 &= \min \left\{ \frac{4C_I^2}{\sigma}, \frac{4C_I^2 h_K^2}{\varepsilon} \right\} \|R_{K,h}(u_h)\|_{L^2(K)}^2, \\ \eta_{\text{Face},F}^2 &= \frac{1}{2} \min \left\{ \frac{4C_F^2 h_F}{\varepsilon}, \frac{4C_F^2}{\sigma^{1/2} \varepsilon^{1/2}} \right\} \|R_F(u_h)\|_{L^2(F)}^2, \\ \eta_{d_h,E}^2 &= \min \left\{ \frac{4\kappa_1 h_E^2}{\varepsilon}, \frac{4\kappa_2}{\sigma} \right\} (1 - \alpha_E)^2 |d_E|^2 h_E^{1-d} \|\nabla u_h \cdot \mathbf{t}_E\|_{L^2(E)}^2\end{aligned}$$

- Using standard bubble function arguments

$$\begin{aligned} \eta_{\text{Int},K} &\leq C \left(\max \left\{ C_K^2 + \frac{C_K h_K}{\varepsilon} \|\mathbf{b}\|_{L^\infty(K)}, \frac{C_K}{\sigma} \|c\|_{L^\infty(K)} \right\} \|u - u_h\|_{a,K} \right. \\ &\quad \left. + \frac{h_K}{\varepsilon^{1/2}} C_K \left(\|f - f_h\|_{0,K} + \|(\mathbf{b} - \mathbf{b}_h) \cdot \nabla u_h\|_{0,K} + \|(c - c_h)u_h\|_{0,K} \right) \right) \end{aligned}$$

- Using standard bubble function arguments

$$\eta_{\text{Int},K} \leq C \left(\max \left\{ C_K^2 + \frac{C_K h_K}{\varepsilon} \|\mathbf{b}\|_{L^\infty(K)}, \frac{C_K}{\sigma} \|c\|_{L^\infty(K)} \right\} \|u - u_h\|_{a,K} + \frac{h_K}{\varepsilon^{1/2}} C_K \left(\|f - f_h\|_{0,K} + \|(\mathbf{b} - \mathbf{b}_h) \cdot \nabla u_h\|_{0,K} + \|(c - c_h)u_h\|_{0,K} \right) \right)$$

and

$$\eta_{\text{Face},F} \leq C \left(\max \left\{ C_F + \frac{C_F h_F \|\mathbf{b}\|_{L^\infty(\omega_F)}}{\varepsilon}, \frac{C_F h_F \|c\|_{L^\infty(\omega_F)}}{\varepsilon^{1/2} \sigma^{1/2}} \right\} \|u - u_h\|_{a,\omega_F} + \delta_{F \in \mathcal{F}_{h,N}} \frac{h_F^{1/2}}{\varepsilon^{1/2}} \|g - g_h\|_{L^2(F)} + \sum_{K \in \omega_F} \left[\eta_{\text{Int},K} + \frac{h_K}{\varepsilon^{1/2}} \left(\|f - f_h\|_{0,K} + \|(\mathbf{b} - \mathbf{b}_h) \cdot \nabla u_h\|_{0,K} + \|(c - c_h)u_h\|_{0,K} \right) \right] \right)$$

- For the stabilization term, from ¹ we get

$$|d_E| \leq C (\varepsilon + \|\mathbf{b}\|_{L^\infty(\Omega)} h + \|c\|_{L^\infty(\Omega)} h^2) h_E^{d-2}$$

¹Barrenechea, John, Knobloch, Rankin: SeMA Journal (75), 655–685, 2018

- For the stabilization term, from ¹ we get

$$|d_E| \leq C (\varepsilon + \|\mathbf{b}\|_{L^\infty(\Omega)} h + \|c\|_{L^\infty(\Omega)} h^2) h_E^{d-2}$$

Hence,

$$\begin{aligned} \eta_{d_h, E} &\leq C \sum_{E \in \mathcal{E}_h} (1 - \alpha_E) (\varepsilon + \|\mathbf{b}\|_{L^\infty(\Omega)} h + \|c\|_{L^\infty(\Omega)} h^2) \\ &\quad \times \frac{h_E^{(3-d)/2}}{\varepsilon^{1/2}} \|\nabla u_h \cdot \mathbf{t}_E\|_{L^2(E)} \end{aligned}$$

¹Barrenechea, John, Knobloch, Rankin: SeMA Journal (75), 655–685, 2018

Theorem (Formal local lower bound)

There exists a constant $C > 0$, independent of the size of elements of \mathcal{T} , such that, for every $K \in \mathcal{T}$, the following formal local lower bound holds

$$\begin{aligned}
 & \eta_{\text{Int},K} + \sum_{K \in \mathcal{F}_h(K)} \eta_{\text{Face},F} + \sum_{E \in \mathcal{E}_h(K)} \eta_{d_h,E} \\
 & \leq \max \left\{ C_K^2 + \frac{C_K h_K}{\varepsilon} \|\mathbf{b}\|_{L^\infty(K)}, \frac{C_K}{\sigma} \|c\|_{L^\infty(K)} \right\} \|u - u_h\|_{a,\omega_K} \\
 & \quad + C \sum_{K \in \omega_K} \frac{h_K}{\varepsilon^{1/2}} \left(\|f - f_h\|_{0,K} + \|(\mathbf{b} - \mathbf{b}_h) \cdot \nabla u_h\|_{0,K} + \|(c - c_h)u_h\|_{0,K} \right) \\
 & \quad + C \sum_{F \in \mathcal{F}_h(K)} \delta_{F \in \mathcal{F}_h,N} \frac{h_F^{1/2}}{\varepsilon^{1/2}} \|g - g_h\|_{L^2(F)} \\
 & \quad + \sum_{E \in \mathcal{E}_h(K)} h^{1-d/2} \frac{h^{1/2}}{\varepsilon^{1/2}} \left(\varepsilon + \|\mathbf{b}\|_{L^\infty(\Omega)} h + \|c\|_{L^\infty(\Omega)} h^2 \right) \|\nabla u_h \cdot \mathbf{t}_E\|_{L^2(E)}.
 \end{aligned}$$

- The initial solution for the nonlinear loop is the SUPG solution ¹
 - u_{AFC} := AFC solution
 - u_{SUPG} := SUPG solution
- By triangle inequality

$$\begin{aligned}\|u - u_{\text{AFC}}\|_a^2 &\leq 2 \left(\|u - u_{\text{SUPG}}\|_a^2 + \|u_{\text{SUPG}} - u_{\text{AFC}}\|_a^2 \right) \\ &\leq 2 \left(\|u - u_{\text{SUPG}}\|_{\text{SUPG}}^2 + \|u_{\text{SUPG}} - u_{\text{AFC}}\|_a^2 \right)\end{aligned}$$

¹ J. John: BAIL 2018 (135), 2020

² John, Novo: CMAME (255), 289-305, 2013

- The initial solution for the nonlinear loop is the SUPG solution ¹
 - u_{AFC} := AFC solution
 - u_{SUPG} := SUPG solution
- By triangle inequality

$$\begin{aligned}\|u - u_{\text{AFC}}\|_a^2 &\leq 2 \left(\|u - u_{\text{SUPG}}\|_a^2 + \|u_{\text{SUPG}} - u_{\text{AFC}}\|_a^2 \right) \\ &\leq 2 \left(\|u - u_{\text{SUPG}}\|_{\text{SUPG}}^2 + \|u_{\text{SUPG}} - u_{\text{AFC}}\|_a^2 \right)\end{aligned}$$

- Using estimators from ²

$$\|u - u_{\text{SUPG}}\|_{\text{SUPG}}^2 \leq \eta_{\text{SUPG}}^2$$

¹ J. John: BAIL 2018 (135), 2020

² John, Novo: CMAME (255), 289-305, 2013

- The initial solution for the nonlinear loop is the SUPG solution ¹
 - u_{AFC} := AFC solution
 - u_{SUPG} := SUPG solution
- By triangle inequality

$$\begin{aligned}\|u - u_{\text{AFC}}\|_a^2 &\leq 2 \left(\|u - u_{\text{SUPG}}\|_a^2 + \|u_{\text{SUPG}} - u_{\text{AFC}}\|_a^2 \right) \\ &\leq 2 \left(\|u - u_{\text{SUPG}}\|_{\text{SUPG}}^2 + \|u_{\text{SUPG}} - u_{\text{AFC}}\|_a^2 \right)\end{aligned}$$

- Using estimators from ²

$$\|u - u_{\text{SUPG}}\|_{\text{SUPG}}^2 \leq \eta_{\text{SUPG}}^2$$

and denoting

$$\eta_{\text{AFC-SUPG}}^2 := \|u_{\text{SUPG}} - u_{\text{AFC}}\|_a^2$$

⇒

$$\|u - u_h\|_a^2 \leq 2 \left(\eta_{\text{SUPG}}^2 + \eta_{\text{AFC-SUPG}}^2 \right)$$

¹J.John: BAIL 2018 (135), 2020

²John, Novo: CMAME (255), 289-305, 2013

- Standard strategy for solving

SOLVE → **ESTIMATE** → **MARK** → **REFINE**

- Effectivity index for the estimator

$$\eta_{\text{eff}} = \frac{\eta}{\|u - u_h\|_a}$$

¹ Kuzmin: in Proc. Int. Conf. Comput. Meth. for Coupled Problems in Science and Engineering, CIMNE, 2007

² Barrenechea, John, Knobloch: M3AS (27), 525–548, 2017

³ Barrenechea, John, Knobloch, Rankin: SeMA Journal (75), 655–685, 2018

- Standard strategy for solving

SOLVE → **ESTIMATE** → **MARK** → **REFINE**

- Effectivity index for the estimator

$$\eta_{\text{eff}} = \frac{\eta}{\|u - u_h\|_a}$$

- Limiters

- Monolithic upwind (MU) limiter¹
- Linearity preservation (LP) limiter²³

¹ Kuzmin: in Proc. Int. Conf. Comput. Meth. for Coupled Problems in Science and Engineering, CIMNE, 2007

² Barrenechea, John, Knobloch: M3AS (27), 525–548, 2017

³ Barrenechea, John, Knobloch, Rankin: SeMA Journal (75), 655–685, 2018

- Comparison of results:
 - On effectivity index (η_{eff})
 - Adaptive grid refinement
 - Behavior of η_{d_h}
 - Behavior of η_{SUPG} and $\eta_{\text{AFC-SUPG}}$
 - Smearing of internal layer¹

¹ John, Knobloch: CMAME (197), 1997–2014, 2008

- Iterative solver for AFC schemes
 - Matrix formulation of the AFC schemes¹²

$$AU + (I - \alpha)DU = F$$

- Fixed point right-hand side

$$(A + D)U^{\nu+1} = F + \omega\alpha DU^{\nu},$$

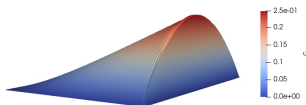
where $\omega > 0$ is a dynamic damping parameter

¹J.John: BAIL 2018 (135), 2020

²J.,John: CAMWA (78), 3117-3138, 2019

- $\Omega = (0, 1)^2$, $\varepsilon = 10^{-3}$, $\mathbf{b} = (2, 1)^T$, $\mathbf{c} = 1$ and f such that

$$u(x, y) = y(1 - y) \left(x - \frac{e^{(x-1)/\varepsilon} - e^{-1/\varepsilon}}{1 - e^{-1/\varepsilon}} \right)$$



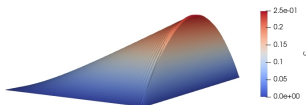
- proposed in ¹
- \mathbb{P}_1 finite elements
- stop of the non linear iteration ²
 - 25000 iterations
 - $\|\text{residual}\|_2 \leq \sqrt{\#\text{nDOFs}} 10^{-10}$

¹ Allendes et. al. : SISC 39(5):A1903-A1927, 2017

² J.,John: CAMWA (78), 3117-3138, 2019

- $\Omega = (0, 1)^2$, $\varepsilon = 10^{-3}$, $\mathbf{b} = (2, 1)^T$, $\mathbf{c} = 1$ and f such that

$$u(x, y) = y(1 - y) \left(x - \frac{e^{(x-1)/\varepsilon} - e^{-1/\varepsilon}}{1 - e^{-1/\varepsilon}} \right)$$



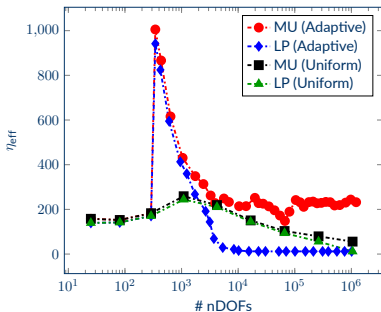
- proposed in ¹
- \mathbb{P}_1 finite elements
- stop of the non linear iteration ²
 - 25000 iterations
 - $\|\text{residual}\|_2 \leq \sqrt{\#\text{nDOFs}} 10^{-10}$
- stop of the adaptive algorithm
 - $\eta \leq 10^{-3}$
 - $\#\text{nDOFs} \approx 10^6$

¹ Allendes et. al. : SISC 39(5):A1903-A1927, 2017

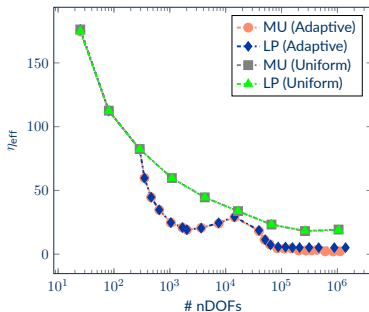
² J.,John: CAMWA (78), 3117-3138, 2019

● Effectivity index

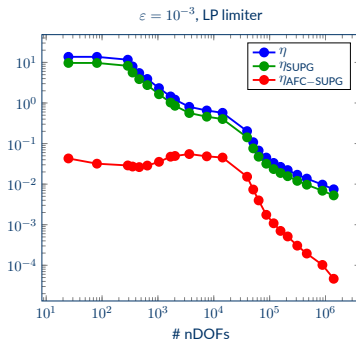
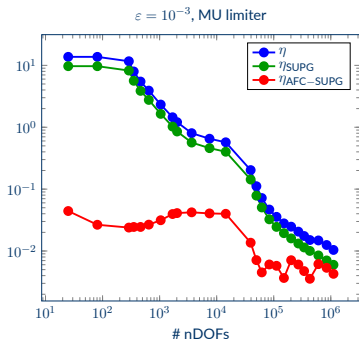
$\varepsilon = 10^{-3}$, Residual Estimator



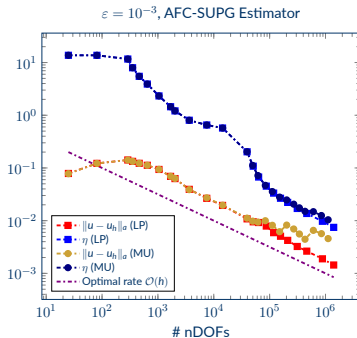
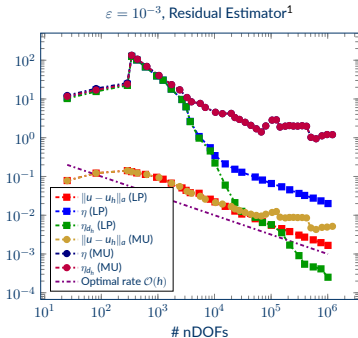
$\varepsilon = 10^{-3}$, AFC-SUPG Estimator



- Comparison of η_{SUPG} and $\eta_{\text{AFC-SUPG}}$



• Errors on adaptive grids



¹Barrenechea, John, Knobloch: SINUM (54), 2427–2451, 2016

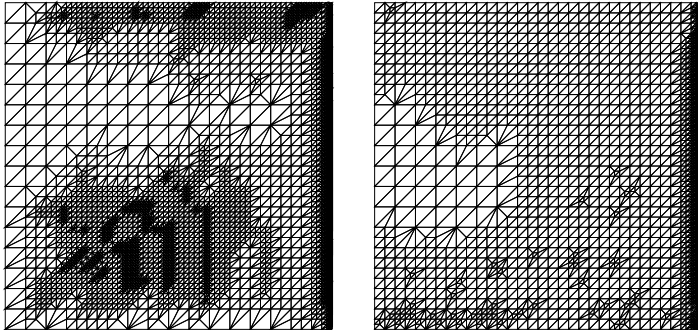
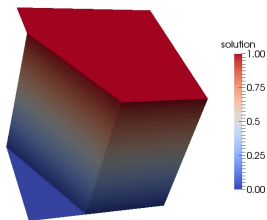


Figure 1: 14th adaptively refined grid with residual estimator. MU limiter (#nDOFs = 22962) (left) and LP limiter (#nDOFs = 23572) (right)

- Example with interior and boundary layer¹
- $\Omega = (0, 1)^2$, $\varepsilon = 10^{-4}$, $\mathbf{b} = (\cos(-\pi/3), \sin(-\pi/3))^T$, $\mathbf{c} = \mathbf{f} = 0$

$$u_b = \begin{cases} 1 & (y = 1 \wedge x > 0) \text{ or } (x = 0 \wedge y > 0.7), \\ 0 & \text{else.} \end{cases}$$



¹Hughes, Mallet, Mizukami: CMAME, 54(3), 341-345, 1986

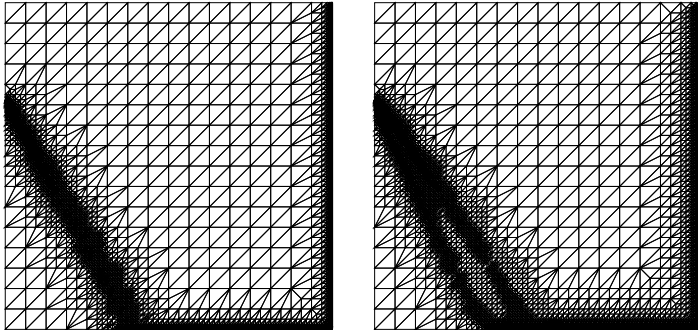
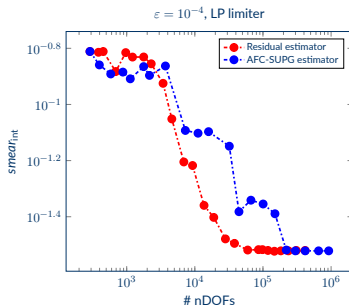
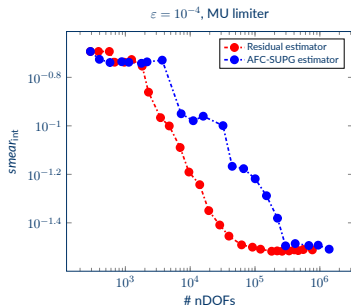


Figure 2: 14th adaptively refined grid for MU limiter. Residual estimator (left) and AFC-SUPG estimator (right)

- Thickness of internal layer



- **Conclusions**¹
 - Effectivity index **not robust** with residual based approach
 - For the **AFC-SUPG estimator**, the effectivity index was **better**
 - Choice of **limiter did not play a role** in AFC-SUPG estimator

¹ Jha: CAMWA, 97(1), 86–99, 2021

² J.,John: CAMWA (78), 3117-3138, 2019

- **Conclusions**¹
 - Effectivity index **not robust** with residual based approach
 - For the **AFC-SUPG estimator**, the effectivity index was **better**
 - Choice of **limiter did not play a role** in AFC-SUPG estimator
 - For the MU limiter with the residual estimator **reduced order of convergence**
 - η_{d_h} is the dominating term in η for MU limiter if problem becomes locally diffusion-dominated. For LP limiter dominating term in the convection-dominated situation
 - With adaptive grid refinement, problem could become **locally diffusion-dominated**. Then use **LP limiter**
 - For a small diffusion coefficient, use MU limiter because **nonlinear problems difficult to solve with LP limiter**²
 - Residual estimator **approximates the internal layer better**

¹ Jha: CAMWA, 97(1), 86–99, 2021

² J.,John: CAMWA (78), 3117-3138, 2019

- Outlook
 - Development of robust estimators
 - Numerical studies in 3D
 - Extending the analysis for the local efficiency of the estimator
 - Interplay of hanging nodes and AFC schemes
 - Comparison with monolithic convex limiter¹

¹Kuzmin: CMAME (361), 112804, 2020