Adaptive Grids for Algebraic Stabilizations of Convection-Diffusion-Reaction Equations

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Joint work with Volker John (WIAS, Berlin) and Petr Knobloch (Charles University, Prague)





Outline

1 Algebraic Stabilisation Schemes

2 A Posteriori Error Analysis 2.1 Residual Based Approach

3 Adaptive Grids 3.1 Implementation

4 Numerical Studies

5 Conclusions and Outlook





Algebraic Stabilisation Schemes A Posteriori Error Analysis Adaptive Grids Numerical Studies Conclusions and Outlook

• Steady-state convection-diffusion-reaction equation

$$-\varepsilon \Delta u + \mathbf{b} \cdot \nabla u + cu = f \quad \text{in } \Omega,$$

$$u = u_b \quad \text{on } \Gamma_D,$$

$$-\varepsilon \nabla u \cdot \mathbf{n} = g \quad \text{on } \Gamma_N$$

- Ω bounded polyhedral Lipschitz domain in \mathbb{R}^d , $d \in \{2, 3\}$
- n outward pointing unit normal
- Assume

$$\left(\mathsf{c}(\mathbf{x}) - \frac{1}{2} \nabla \cdot \mathbf{b}(\mathbf{x})\right) \ge \sigma_0 > 0$$

Interested in convection-dominated regime, ε ≪ ||b||_{L∞(Ω)}L
L - Characteristic length of the problem



- Ideal discretization
 - 1. Accurate and sharp layers





Algebraic Stabilisation Schemes A Posteriori Error Analysis Adaptive Grids Numerical Studies Conclusions and Outlook

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- 2. Physically consistent results (no spurious oscillations)





Algebraic Stabilisation Schemes A Posteriori Error Analysis Adaptive Grids Numerical Studies Conclusions and Outlook

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- 2. Physically consistent results (no spurious oscillations)
- 3. Efficient computation of the solutions





Algebraic Stabilisation Schemes A Posteriori Error Analysis Adaptive Grids Numerical Studies Conclusions and Outlook

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- 3. Efficient computation of the solutions
- Because of 2nd property: Algebraic stabilised schemes very well suited for applications





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- 1. Accurate and sharp layers
- 2. Physically consistent results (no spurious oscillations)
- 3. Efficient computation of the solutions
- Because of 2nd property: Algebraic stabilised schemes very well suited for applications
- Alternate approach: Adaptive grids





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- 1. Accurate and sharp layers
- 2. Physically consistent results (no spurious oscillations)
- 3. Efficient computation of the solutions
- Because of 2nd property: Algebraic stabilised schemes very well suited for applications
- Alternate approach: Adaptive grids
- Idea: Combine both the approaches





A Posteriori Analysis

Algebraic Stabilisation Schemes A Posteriori Error Analysis Adaptive Grids Numerical Studies Conclusions and Outlook

• Variational problem for AFC scheme¹ Find $u_h \in V_h$ such that

 $a_h(\mathbf{u}_h, \mathbf{v}_h) + d_h(\mathbf{u}_h; \mathbf{u}_h, \mathbf{v}_h) = \langle f, \mathbf{v}_h \rangle \ \forall \mathbf{v}_h \in \mathbf{V}_h$

 $\circ~V_h-$ finite element space with homogeneous Dirichlet boundary conditions $(V_h\subset V)$

¹Barrenechea, John, Knobloch: arXiv : 2204.07480, 2022





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- $\circ~V_h-$ finite element space with homogeneous Dirichlet boundary conditions $(V_h\subset V)$
- stabilization

$$d_{\mathsf{h}}(\mathsf{w}; \mathsf{z}, \mathsf{v}) = \sum_{i,j=1}^{\mathsf{N}} (1 - \alpha_{ij}(\mathsf{w})) d_{ij}(\mathsf{z}_j - \mathsf{z}_i) \mathsf{v}_i \quad \forall \ \mathsf{w}, \mathsf{v}, \mathsf{z} \in \mathsf{V}_{\mathsf{h}}$$

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Energy norm

$$\|u_h\|_a^2 = \varepsilon |u_h|_1^2 + \sigma \|u_h\|_0^2$$

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Residual Based Approach

Algebraic Stabilisation Schemes A Posteriori Error Analysis Adaptive Grids Numerical Studies Conclusions and Outlook

Theorem (Global a posteriori error estimate)

A global a posteriori error estimate for the energy norm is given by¹

 $\|\mathbf{u}-\mathbf{u}_{h}\|_{a}^{2} \leq \eta_{1}^{2}+\eta_{2}^{2}+\eta_{3}^{2},$

where

$$\eta_1^2 = \sum_{K \in \mathcal{T}_h} \min\left\{\frac{4C_l^2}{\sigma}, \frac{4C_l^2 h_K^2}{\varepsilon}\right\} \|R_K(u_h)\|_{L^2(K)}^2,$$

$$\eta_2^2 = \sum_{F \in \mathcal{F}_h} \min\left\{\frac{4C_F^2 h_F}{\varepsilon}, \frac{4C_F^2}{\sigma^{1/2} \varepsilon^{1/2}}\right\} \|R_F(u_h)\|_{L^2(F)}^2,$$

$$\eta_3^2 = \sum_{E \in \mathcal{E}_h} \min\left\{\frac{4\kappa_1 h_E^2}{\varepsilon}, \frac{4\kappa_2}{\sigma}\right\} (1 - \alpha_E)^2 |d_E|^2 h_E^{1-d} \|\nabla u_h \cdot \mathbf{t}_E\|_{L^2(E)}^2$$

¹J.: CAMWA, 97(1), 86–99, 2021



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Hanging Nodes

Algebraic Stabilisation Schemes A Posteriori Error Analysis Adaptive Grids Numerical Studies Conclusions and Outlook

• Standard strategy for solving

$\textbf{SOLVE} \rightarrow \textbf{ESTIMATE} \rightarrow \textbf{MARK} \rightarrow \textbf{REFINE}$

¹Xu, Zikatanov: MC, 68(228), 1429–1446, 1999





• Standard strategy for solving

$\textbf{SOLVE} \rightarrow \textbf{ESTIMATE} \rightarrow \textbf{MARK} \rightarrow \textbf{REFINE}$

• Hanging nodes

- Preserves angles after red-refinement
- Avoids prism and pyramids in 3D mesh refinement
- hp adaptive refinement
- Certain stabilized schemes rely on the property of triangulation ¹

¹Xu, Zikatanov: MC, 68(228), 1429–1446, 1999





Adaptive Grids

Algebraic Stabilisation Schemes A Posteriori Error Analysis Adaptive Grids Numerical Studies Conclusions and Outlook

Lemma

Let \mathcal{T} be a non-conforming triangulation of Ω , i.e., \mathcal{T} has hanging nodes. Then, for all $q \in H(\mathcal{T})$ there are coefficients a_{qp} with $p \in N_F(\mathcal{T}) \setminus H(\mathcal{T})$ such that all $v \in V_h$ can be represented as^{1,2}

$$\mathbf{v}(q) = \sum_{\mathbf{p} \in \mathbf{N}_{\mathbf{F}}(\mathcal{T}) \setminus \mathbf{H}(\mathcal{T})} a_{qp} \mathbf{v}(\mathbf{p})$$

¹Gräser : PhD Thesis, FU Berlin 2011

² J.: PhD Thesis, FU Berlin 2020



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$$\mathbf{v}(q) = \sum_{\mathbf{p} \in \mathbf{N}_{\mathbf{F}}(\mathcal{T}) \setminus \mathbf{H}(\mathcal{T})} a_{qp} \mathbf{v}(\mathbf{p})$$

Theorem

Let $\{\mathcal{T}_0, \cdots, \mathcal{T}_j\}$ be a grid hierarchy on Ω with \mathcal{T}_0 being conforming. Let us denote $\mathcal{T} = \mathcal{T}_j$, i.e., the final refinement level. Then a basis of V_h is given by ¹

$$\mathsf{B}(\mathcal{T}) := \left\{ \varphi_{p} = \varphi_{p}^{\mathsf{nc}} + \sum_{q \in \mathsf{H}(\mathcal{T})} a_{qp} \varphi_{q}^{\mathsf{nc}} : p \in \mathsf{N}_{\mathsf{F}}(\mathcal{T}) \setminus \mathsf{H}(\mathcal{T}) \right\}$$

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- Satisfaction of DMP
 - DMP is satisfied if¹

 $\begin{array}{rcl} a_{ii} &>& 0,\\ a_{ij}+a_{ji} &\leq& 0, \end{array}$

where a_{ij} is in the stiffness matrix

¹Barrenechea, John, Knobloch: SINUM (54), 2427–2451, 2016





Implementation

• Consider the sample patch







• Initial assembly

(<i>a</i> ₀₀	a 01	a_{02}	a 03	a ₀₄		$\left(b_{0} \right)$
a ₁₀	a ₁₁	a_{12}	a ₁₃	a ₁₄		b ₁
a ₂₀	a_{21}	a_{22}	a_{23}	a_{24}	,	b_2
<i>a</i> ₃₀	a_{31}	a_{32}	a ₃₃	a_{34}		b ₃
a_{40}	a_{41}	a_{42}	a_{43}	a ₄₄)		b_4





• Initial assembly

$$\begin{pmatrix} a_{00} & a_{01} & a_{02} & a_{03} & a_{04} \\ a_{10} & a_{11} & a_{12} & a_{13} & a_{14} \\ a_{20} & a_{21} & a_{22} & a_{23} & a_{24} \\ a_{30} & a_{31} & a_{32} & a_{33} & a_{34} \\ a_{40} & a_{41} & a_{42} & a_{43} & a_{44} \end{pmatrix}, \quad \begin{pmatrix} b_0 \\ b_1 \\ b_2 \\ b_3 \\ b_4 \end{pmatrix}$$

• Conforming test space and continuity of the hanging node

$$\begin{pmatrix} 1 & -\frac{1}{2} & 0 & -\frac{1}{2} & 0 \\ a_{10} + \frac{a_{00}}{2} & a_{11} + \frac{a_{01}}{2} & a_{12} + \frac{a_{02}}{2} & a_{13} + \frac{a_{03}}{2} & a_{14} + \frac{a_{04}}{2} \\ a_{20} & a_{21} & a_{22} & a_{23} & a_{24} \\ a_{30} + \frac{a_{00}}{2} & a_{31} + \frac{a_{01}}{2} & a_{32} + \frac{a_{02}}{2} & a_{33} + \frac{a_{03}}{2} & a_{34} + \frac{a_{04}}{2} \\ a_{40} & a_{41} & a_{42} & a_{43} & a_{44} \end{pmatrix}, \quad \begin{pmatrix} 0 \\ b_1 + \frac{b_0}{2} \\ b_2 \\ b_3 + \frac{b_0}{2} \\ b_4 \end{pmatrix}$$





Implementation

• Conforming ansatz space

$$\begin{pmatrix} 1 & -\frac{1}{2} & 0 & -\frac{1}{2} & 0 \\ 0 & a_{11} + \frac{a_{01}}{2} + \frac{a_{10}}{2} + \frac{a_{00}}{4} & a_{12} + \frac{a_{02}}{2} & a_{13} + \frac{a_{03}}{2} + \frac{a_{10}}{2} + \frac{a_{00}}{4} & a_{14} + \frac{a_{04}}{2} \\ 0 & a_{21} + \frac{a_{20}}{2} & a_{22} & a_{23} + \frac{a_{20}}{2} & a_{24} \\ 0 & a_{31} + \frac{a_{01}}{2} + \frac{a_{30}}{2} + \frac{a_{00}}{4} & a_{32} + \frac{a_{02}}{2} & a_{33} + \frac{a_{03}}{2} + \frac{a_{30}}{2} + \frac{a_{00}}{4} & a_{34} + \frac{a_{04}}{2} \\ 0 & a_{41} + \frac{a_{40}}{2} & a_{42} & a_{43} + \frac{a_{40}}{2} & a_{44} \end{pmatrix}$$





Implementation

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$$\begin{pmatrix} 1 & -\frac{1}{2} & 0 & -\frac{1}{2} & 0 \\ 0 & a_{11} + \frac{a_{01}}{2} + \frac{a_{10}}{2} + \frac{a_{00}}{4} & a_{12} + \frac{a_{02}}{2} & a_{13} + \frac{a_{03}}{2} + \frac{a_{10}}{2} + \frac{a_{00}}{4} & a_{14} + \frac{a_{04}}{2} \\ 0 & a_{21} + \frac{a_{20}}{2} & a_{22} & a_{23} + \frac{a_{20}}{2} & a_{24} \\ 0 & a_{31} + \frac{a_{01}}{2} + \frac{a_{30}}{2} + \frac{a_{00}}{4} & a_{32} + \frac{a_{02}}{2} & a_{33} + \frac{a_{03}}{2} + \frac{a_{30}}{2} + \frac{a_{00}}{4} & a_{34} + \frac{a_{04}}{2} \\ 0 & a_{41} + \frac{a_{40}}{2} & a_{42} & a_{43} + \frac{a_{40}}{2} & a_{44} \end{pmatrix}$$

• Increases the matrix stencil by few elements





Algebraic Stabilisation Schemes A Posteriori Error Analysis Adaptive Grids Numerical Studies Conclusions and Outlook

- Algebraic stabilisation schemes
 - Algebraic Flux Correction (AFC) schemes
 - Kuzmin limiter¹
 - BJK limiter^{2,3}

⁴ John, Knobloch: arXiv: 2111.08697, 2021



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¹Kuzmin: in Proc. Int. Conf. Comput. Meth. for Coupled Problems in Science and Engineering, CIMNE, 2007

²Barrenechea, John, Knobloch: M3AS (27), 525-548, 2017

³Barrenechea, John, Knobloch: arXiv: 2204.07480, 2022

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- Algebraic stabilisation schemes
 - Algebraic Flux Correction (AFC) schemes
 - Kuzmin limiter¹
 - BJK limiter^{2,3}
 - Monotone Upwind-type Algebraically Stabilized (MUAS) method⁴
 - **Drops** symmetric condition on α_{ij}
 - AFC system is modified

$$(\mathbf{A} + \mathbf{D}) \mathbf{U} = \mathbf{F} + (\mathbf{D} - \mathbf{B}) \mathbf{U},$$

where

$$b_{ij} = \max\left\{\left(1 - \overline{\alpha_{ij}}(\mathsf{u})\right)a_{ij}, 0, \left(1 - \overline{\alpha_{ji}}(\mathsf{u})\right)a_{ji}\right\}$$

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- Comparison of results:
 - Accuracy of solution
 - $\|\cdot\|_{L^2(\Omega)} \\ \|\nabla(\cdot)\|_{L^2(\Omega)}$

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 - $\begin{array}{l} \|\cdot\|_{L^2(\Omega)} \\ \|\nabla(\cdot)\|_{L^2(\Omega)} \end{array}$
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 - Efficiency of the scheme
 - Global satisfaction of DMP

$$\operatorname{osc}_{\max}(u_h) := \max_{(x,y)\in\overline{\Omega}} u_h(x,y) - 1 - \min_{(x,y)\in\overline{\Omega}} u_h(x,y)$$

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• Smearing of internal layer¹



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Adaptive grids



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- For MUAS method neglect η_3

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• Iterative solver

 $\circ~$ Matrix formulation of the algebraic stabilised schemes 1,2

$$(\mathsf{A} + \mathsf{D}) \mathsf{U} = \mathsf{F} + (\mathsf{D} - \mathsf{B}(\mathsf{U})) \mathsf{U}$$

• Fixed point right-hand side

where $\omega > 0$ is a dynamic damping parameter

² J., John: CAMWA (78), 3117-3138, 2019





¹J.John: BAIL 2018 (135), 2020

Algebraic Stabilisation Schemes A Posteriori Error Analysis Adaptive Grids Numerical Studies Conclusions and Outlook

- Example with corner boundary layer¹
- $\Omega = (0, 1)^2, \varepsilon = 10^{-2}, \mathbf{b} = (2, 3)^T, \mathbf{c} = 1, u_b = 0, \mathbf{g} = 0$, and f such that

$$\mathsf{u}(\mathsf{x},\mathsf{y}) = \mathsf{x}\mathsf{y}^2 - \mathsf{y}^2 \exp\left(\frac{2(\mathsf{x}-1)}{\varepsilon}\right) - \mathsf{x}\exp\left(\frac{3(\mathsf{y}-1)}{\varepsilon}\right) + \exp\left(\frac{2(\mathsf{x}-1) + 3(\mathsf{y}-1)}{\varepsilon}\right)$$



- stop of the non linear iteration ²
 - o 10000 iterations
 - $\|\operatorname{residual}\|_2 \leq \sqrt{\#\operatorname{dof}} 10^{-10}$

¹John, Knobloch, Savescu: CMAME (200), 2916–2929, 2011

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- stop of the non linear iteration ²
 - 10000 iterations
 - $\|\operatorname{residual}\|_2 \leq \sqrt{\#\operatorname{dof}} 10^{-10}$
- stop of the adaptive algorithm

•
$$\eta \le 10^{-3}$$

•
$$\#dof \approx 10^6$$

¹ John, Knobloch, Savescu: CMAME (200), 2916–2929, 2011

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• $L^2(\Omega)$ Error







• $L^2(\Omega)$ Error of the gradient





Un

• Efficiency







Algebraic Stabilisation Schemes A Posteriori Error Analysis Adaptive Grids Numerical Studies Conclusions and Outlook

- Hemker problem¹
- $\varepsilon = 10^{-4}$, $\mathbf{b} = (1, 0)^T$, $\mathbf{c} = \mathbf{f} = 0$





- stop of the non linear iteration
 - \circ 10000 iterations
 - $\|\operatorname{residual}\|_2 \le \sqrt{\#\operatorname{dof}} 10^{-8}$

¹Hemker: JCAM 76, 277-285, 1996





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- stop of the non linear iteration
 - \circ 10000 iterations
 - $\circ \||\mathbf{residual}||_2 \leq \sqrt{\#\mathbf{dof}} 10^{-8}$
- stop of the adaptive algorithm

$$\circ \ \eta \leq 10^{-3}$$

o #dof $\approx 5 \times 10^5$

¹Hemker: JCAM 76, 277-285, 1996





• Satisfaction of Global DMP







• Smearing of internal layer







Algebraic Stabilisation Schemes A Posteriori Error Analysis Adaptive Grids Numerical Studies Conclusions and Outlook



Figure 1: Adaptively refined conforming grids with $\approx 25,000$ #dof, AFC method and Kuzmin limiter (left), MUAS method (right)





• Efficiency







Conclusions and Outlook

Algebraic Stabilisation Schemes A Posteriori Error Analysis Adaptive Grids Numerical Studies Conclusions and Outlook

- Conclusions¹
 - Accuracy of solution
 - AFC + BJK limiter and MUAS method converge on all grids
 - AFC + Kuzmin limiter does not converge on adaptively refined grids if solution becomes (locally) diffusion-dominated

¹ J.,John, Knobloch: arXiv : 2007.08405 , 2022

²J.,John: CAMWA (78), 3117-3138, 2019



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Adaptive Grids for Algebraic Stabilization, 1st March 2023



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Conclusions and Outlook

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 - AFC+ Kuzmin limiter and the MUAS method² most efficient

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Adaptive Grids for Algebraic Stabilization, 1st March 2023



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 - Satisfaction of DMP
 - Global DMP satisfied on grids with hanging nodes
 - AFC+ Kuzmin limiter did not satisfy on conformally closed grids

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 - Smearing
 - AFC + BJK limiter sharpest layer
 - For fine grids, all values close to reference value

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 - For fine grids, all values close to reference value
- MUAS method most promising
 - ¹ J.,John, Knobloch: arXiv : 2007.08405 , 2022
 - ²J.,John: CAMWA (78), 3117-3138, 2019



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Outlook

- Development of estimators for MUAS method
- Numerical studies in 3D
- Comparison with Monolithic Convex Limiter¹²

¹Kuzmin: CMAME (361), 112804, 2020

² J., Partl, Ahmed, Kuzmin: JNUM, 10.1515/jnma-2021-0123, 2022



