

Overview of the Domain Decomposition Method for the Linear Poisson Boltzmann Equations

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Joint work with M.Nottoli (Universität Stuttgart, Stuttgart), A.Mikhalev (RWTH Aachen University, Aachen),
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- 1 Solvation Models
- 2 ddLPB Method
- 3 ddLPB Derivation
- 4 Computation of Forces
- 5 Numerical Studies
- 6 Conclusions and Outlook

- Ionic Solvation Models¹
 - Explicit Solvation Models
 - Adopts molecular representation of both solute and solvent
 - Accurate results
 - Computationally expensive

¹Zhang et. al.: JCTC, 13, 1034-1043, 2017

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- Ionic Solvation Models¹
 - Explicit Solvation Models
 - Adopts molecular representation of both solute and solvent
 - Accurate results
 - Computationally expensive
 - Implicit Solvation Models^{2,3}
 - Microscopic treatment of solute
 - Macroscopic treatment of solvent using physical properties
 - Less computational cost

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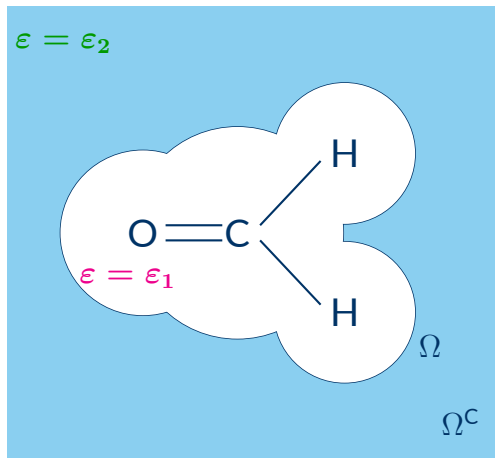


Figure 1: Formaldehyde molecule

- Linear Poisson-Boltzman (LPB) equation

$$-\nabla \cdot [\varepsilon(\mathbf{x}) \nabla \psi(\mathbf{x})] + \bar{\kappa}(\mathbf{x})^2 \psi(\mathbf{x}) = 4\pi \rho_M(\mathbf{x}) \quad \text{in } \mathbb{R}^3$$

- $\psi(\mathbf{x})$ – Electrostatic potential

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- $\psi(\mathbf{x})$ – Electrostatic potential
- $\varepsilon(\mathbf{x})$ – Space-dependent dielectric permittivity

$$\varepsilon(\mathbf{x}) = \begin{cases} \varepsilon_1 & \text{in } \Omega, \\ \varepsilon_2 & \text{in } \Omega^C := \mathbb{R}^3 \setminus \bar{\Omega} \end{cases}$$

- Ω – Solute Cavity

- $\bar{\kappa}(\mathbf{x})$ – Modified Debye-Hückel parameter

$$\bar{\kappa}(\mathbf{x}) = \begin{cases} 0 & \text{in } \Omega, \\ \sqrt{\varepsilon_2} \kappa & \text{in } \Omega^c \end{cases}$$

- κ – Debye-Hückel screening constant

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- κ – Debye-Hückel screening constant
- $\rho_M(\mathbf{x})$ – Solute charge distribution

$$\rho_M(\mathbf{x}) = \sum_{i=1}^M q_i \delta(\mathbf{x} - \mathbf{x}_i)$$

- M – Number of solute atoms
- q_i – Partial charge on the i^{th} atom

- **Boundary Element Method (BEM)** ¹

¹Yoon, Lehnoff: JCC 11, 1080–1086, 1990

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³Chen, Holst, Xu: SINUM 45, 2295–2320, 2007

⁴Cancés, Maday, Stamm: JCP 139, 054111, 2013

⁵Lipparini et.al.: JCP 141, 184108, 2014

⁶Quan, Stamm, Maday: SISC 41, B320–B350, 2019

⁷Lebedev, Laikov: DM 59, 477–481, 1999

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- **Finite Difference Method (FDM)**²

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- **Boundary Element Method (BEM)**¹
- **Finite Difference Method (FDM)**²
- **Finite Element Method (FEM)**³
- **Domain Decomposition Methods**^{4,5,6}
 - **Schwarz decomposition method**
 - **Does not rely on mesh** but **quadrature points**⁷
 - **Computation of forces** becomes **natural** as spheres are centered at nucleus position

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- The LPB equation can be written in two equations

$$\begin{aligned} -\Delta\psi(\mathbf{x}) &= \frac{4\pi}{\epsilon_1} \rho_M(\mathbf{x}) && \text{in } \Omega, \\ -\Delta\psi(\mathbf{x}) + \kappa^2\psi(\mathbf{x}) &= 0 && \text{in } \Omega^C, \end{aligned}$$

with

$$\begin{aligned} \llbracket \psi(\mathbf{x}) \rrbracket &= 0 && \text{on } \Gamma = \partial\Omega, \\ \llbracket \partial_n(\epsilon\psi)(\mathbf{x}) \rrbracket &= 0 && \text{on } \Gamma \end{aligned}$$

- Using potential theory the final equations are

$$-\Delta\psi_r(\mathbf{x}) = 0 \quad \text{in } \Omega,$$

$$-\Delta\psi_e(\mathbf{x}) + \kappa^2\psi_e(\mathbf{x}) = 0 \quad \text{in } \Omega,$$

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with

$$\psi_0 + \psi_r = \psi_e \quad \text{on } \Gamma,$$

$$\sigma_e = \partial_n\psi_e - \frac{\epsilon_1}{\epsilon_2}\partial_n(\psi_0 + \psi_r) \quad \text{on } \Gamma^1$$

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where

- ψ_r – Reaction potential in Ω
- ψ_0 – Potential generated by ρ_M satisfying,

$$-\Delta\psi_0 = \frac{4\pi}{\epsilon_1} \rho_M$$

¹Sauter, Schwab, Springer, Berlin-2011, Thm. 3.3.1

- ψ_e – Extended potential from Ω^C to Ω
- σ_e – Charge density generating ψ_e satisfying

$$S_\kappa \sigma_e(x) := \int_\Gamma \frac{\exp(-\kappa|x-y|) \sigma_e(y)}{4\pi|x-y|} = \psi_e \quad \forall x \in \Gamma$$

- S_κ – Invertible single-layer potential operator¹

$$S_\kappa : H^{-1/2}(\Gamma) \rightarrow H^{1/2}(\Gamma)$$

¹Sauter, Schwab, Springer, Berlin-2011, 101-181

$-\Delta\psi + \kappa^2\psi = 0$

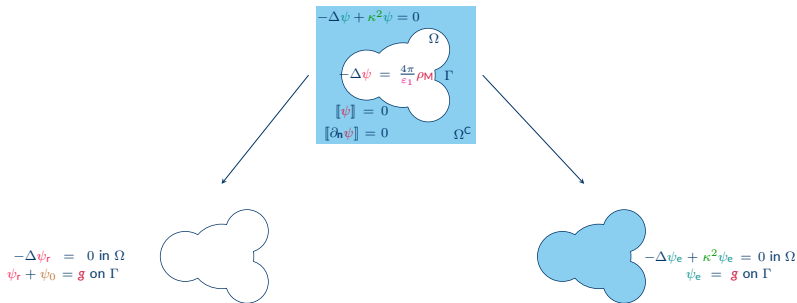
$-\Delta\psi = \frac{4\pi}{\epsilon_1}\rho_M \quad \Gamma$

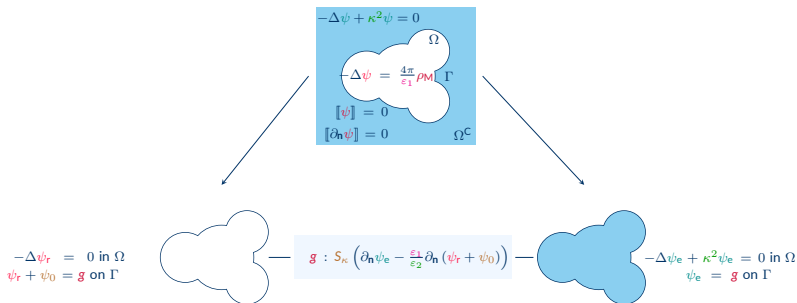
$[\psi] = 0$

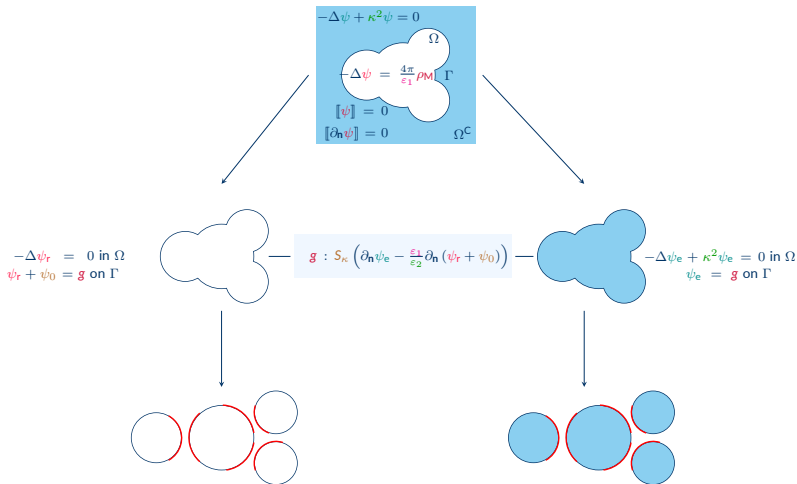
$[\partial_n\psi] = 0$

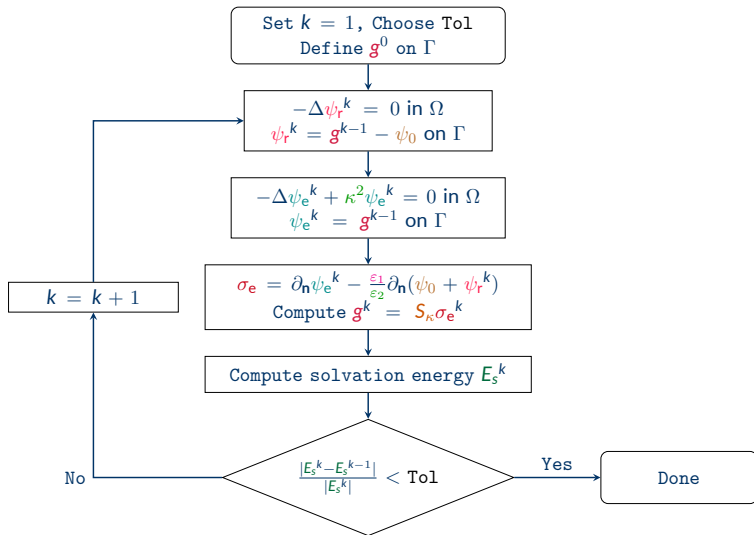
Ω

Ω^C









- According to definition of Ω

$$\Omega = \bigcup_{j=1}^M \Omega_j, \quad \Omega_j = B_{r_j}(\mathbf{x}_j)$$

- Laplace equation restricted to Ω_j

$$\begin{aligned} -\Delta \psi_r|_{\Omega_j} &= 0 && \text{in } \Omega_j, \\ \psi_r|_{\Gamma_j} &= \phi_{r,j} && \text{on } \Gamma_j \end{aligned}$$

where

$$\phi_{r,j} = \begin{cases} \psi_r & \text{on } \Gamma_j^i, \\ \mathbf{g} - \psi_0 & \text{on } \Gamma_j^e \end{cases}$$

- HSP equation restricted to Ω_j

$$\begin{aligned} -\Delta\psi_e|_{\Omega_j} + \kappa^2\psi_e|_{\Omega_j} &= 0 && \text{in } \Omega_j, \\ \psi_e|_{\Gamma_j} &= \phi_{e,j} && \text{on } \Gamma_j \end{aligned}$$

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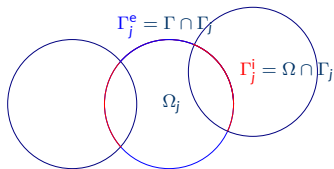


Figure 2: 2-D schematic diagram of Γ_j^i and Γ_j^e

- Laplace equation in unit ball

$$\begin{aligned} -\Delta u_r &= 0 && \text{in } B_1(0), \\ u_r &= \phi_r && \text{on } \mathbb{S}^2 \end{aligned}$$

- Unique solution in $H^1(B_1(0))$

$$u_r(r, \theta, \varphi) = \sum_{\ell=0}^{\infty} \sum_{m=-\ell}^{\ell} [\phi_r]_{\ell}^m r^{\ell} Y_{\ell}^m(\theta, \varphi)$$

for $0 \leq r \leq 1$, $0 \leq \theta \leq \pi$, $0 \leq \varphi < 2\pi$

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where

- Y_{ℓ}^m – (Real orthonormal) spherical harmonics of degree ℓ and order m on \mathbb{S}^2
- $[\phi_r]_{\ell}^m$ – Real coefficient of u_r corresponding to Y_{ℓ}^m

$$[\phi_r]_{\ell}^m = \int_{\mathbb{S}^2} \phi_r(s) Y_{\ell}^m(s) ds$$

- u_r can be numerically approximated by \tilde{u}_r

$$\tilde{u}_r(r, \theta, \varphi) = \sum_{l=0}^{l_{\max}} \sum_{m=-l}^l \left[\tilde{\phi}_r \right]_l^m r^l Y_l^m(\theta, \varphi)$$

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where

- ℓ_{\max} – Maximum degree of Y_{ℓ}^m
- $[\tilde{\phi}_r]_{\ell}^m$ – Numerical approximation of $[\phi_r]_{\ell}^m$

$$[\tilde{\phi}_r]_{\ell}^m = \sum_{n=1}^{N_{\text{leb}}} \omega_n^{\text{leb}} \phi_r(s_n) Y_{\ell}^m(s_n)$$

- $s_n \in \mathbb{S}^2$ – Lebedev quadrature points
- ω_n^{leb} – Lebedev quadrature weights
- N_{leb} – Number of Lebedev quadrature points

- HSP equation in unit ball

$$\begin{aligned} -\Delta u_e + \kappa^2 u_e^2 &= 0 && \text{in } B_1(0), \\ u_e &= \phi_e && \text{on } \mathbb{S}^2 \end{aligned}$$

- Unique solution

$$u_e(r, \theta, \varphi) = \sum_{\ell=0}^{\infty} \sum_{m=-\ell}^{\ell} [\phi_e]_{\ell}^m i_{\ell}(r) Y_{\ell}^m(\theta, \varphi)$$

for $0 \leq r \leq 1$, $0 \leq \theta \leq \pi$, $0 \leq \varphi < 2\pi$

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for $0 \leq r \leq 1$, $0 \leq \theta \leq \pi$, $0 \leq \varphi < 2\pi$

where

- $[\phi_e]_{\ell}^m$ – Coefficient of Y_{ℓ}^m
- $i_{\ell}(r)$ – Bessel functions of the first kind

- u_e can be numerically approximated by \tilde{u}_e

$$\tilde{u}_e(r, \theta, \varphi) = \sum_{\ell=0}^{\ell_{\max}} \sum_{m=-\ell}^{\ell} \left[\tilde{\phi}_e \right]_{\ell}^m \frac{i_{\ell}(r)}{i_{\ell}(1)} Y_{\ell}^m(\theta, \varphi)$$

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for $0 \leq r \leq 1$, $0 \leq \theta \leq \pi$, $0 \leq \varphi < 2\pi$

where

- $\left[\tilde{\phi}_e \right]_{\ell}^m$ – Numerical approximation of $\left[\phi_e \right]_{\ell}^m$

$$\left[\tilde{\phi}_e \right]_{\ell}^m = \sum_{n=1}^{N_{\text{leb}}} \omega_n^{\text{leb}} \phi_e(s_n) Y_{\ell}^m(s_n)$$

- Rewriting the coupling equations as

$$\psi_r|_{\Gamma_j}(\mathbf{x}) - \sum_{i \neq j} \omega_{ji}(\mathbf{x}) \psi_r|_{\Omega_i}(\mathbf{x}) = \chi_j^e(\mathbf{x}) (\mathbf{g}(\mathbf{x}) - \psi_0(\mathbf{x})) \quad \forall \mathbf{x} \in \Gamma_j$$

and

$$\psi_e|_{\Gamma_j}(\mathbf{x}) - \sum_{i \neq j} \omega_{ji}(\mathbf{x}) \psi_e|_{\Omega_i}(\mathbf{x}) = \chi_j^e(\mathbf{x}) \mathbf{g}(\mathbf{x}) \quad \forall \mathbf{x} \in \Gamma_j$$

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where

$$\circ \chi_j^e(\mathbf{x}) := \begin{cases} 1 & \text{if } \mathbf{x} \in \Gamma_j^e, \\ 0 & \text{if } \mathbf{x} \in \Gamma_j^i. \end{cases}, \quad \omega_{ji}(\mathbf{x}) := \frac{\chi_i(\mathbf{x})}{\sum_{k \neq j} \chi_k(\mathbf{x})}$$

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where

- $\chi_j^e(\mathbf{x}) := \begin{cases} 1 & \text{if } \mathbf{x} \in \Gamma_j^e, \\ 0 & \text{if } \mathbf{x} \in \Gamma_j^i. \end{cases}$, $\omega_{ji}(\mathbf{x}) := \frac{\chi_i(\mathbf{x})}{\sum_{k \neq j} \chi_k(\mathbf{x})}$
- $\chi_j^e(\mathbf{x}) = 1 - \sum_{i \neq j} \omega_{ji}(\mathbf{x}) \quad \forall \mathbf{x} \in \Gamma_j$

- Reformulating the global coupling condition over each sphere Γ_i

$$g(\mathbf{x}) = \sum_{i=1}^M \tilde{S}_{\kappa, \Gamma_i} \left[\chi_i^e \left(\partial_{\mathbf{n}} \psi_e - \frac{\epsilon_1}{\epsilon_2} \partial_{\mathbf{n}} (\psi_0 + \psi_r) \right) \right] (\mathbf{x}) \quad \forall \mathbf{x} \in \Gamma$$

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where

○

$$\tilde{S}_{\kappa, \Gamma_i} \sigma_e(\mathbf{x}) := \int_{\Gamma_i} \frac{\exp(-\kappa|\mathbf{x} - \mathbf{y}|) \sigma_e(\mathbf{y})}{4\pi|\mathbf{x} - \mathbf{y}|} \quad \forall \mathbf{x} \in \mathbb{R}^3$$

- Using $x (\in \Gamma_j) = x_j + r_j s$ for $s \in \mathbb{S}^2$, the coupling equation is

$$\begin{aligned} \psi_r|_{\Gamma_j}(x_j + r_j s) - \sum_{i \neq j} \omega_{ji}(x_j + r_j s) \psi_r|_{\Omega_i}(x_j + r_j s) \\ = \chi_j^e(x_j + r_j s) (g(x_j + r_j s) - \psi_0(x_j + r_j s)) \end{aligned}$$

- Multiplying by Y_ℓ^m and integrating over \mathbb{S}^2

$$\begin{aligned} \left\langle \psi_r|_{\Gamma_j}(x_j + r_j \bullet) - \sum_{i \neq j} \omega_{ji}(x_j + r_j \bullet) \psi_r|_{\Omega_i}(x_j + r_j \bullet), Y_\ell^m(\bullet) \right\rangle_{\mathbb{S}^2} \\ = \left\langle \chi_j^e(x_j + r_j \bullet) (g(x_j + r_j \bullet) - \psi_0(x_j + r_j \bullet)), Y_\ell^m(\bullet) \right\rangle_{\mathbb{S}^2} \quad \forall j, \ell, m \end{aligned}$$

- Moving from unit ball to Ω_i

$$\psi_r|_{\Omega_i}(x_i + rs) = \sum_{\ell'=0}^{\ell_{\max}} \sum_{m'=-\ell'}^{\ell'} [X_r]_{i\ell'm'} \left(\frac{r}{r_i}\right)^{\ell'} Y_{\ell'}^{m'}(s), \quad 0 \leq r \leq r_i, s \in \mathbb{S}^2$$

and

$$\partial_{\mathbf{n}} \psi_r(x_i + rs) = \sum_{\ell'=0}^{\ell_{\max}} \sum_{m'=-\ell'}^{\ell'} [X_r]_{i\ell'm'} \left(\frac{\ell'}{r_i}\right) Y_{\ell'}^{m'}(s), \quad x_i + r_i s \in \Gamma_i^e$$

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- $[X_r]_{j\ell m}$ – Unknown coefficients of the mode Y_{ℓ}^m

- Using Lebedev quadrature the final linear system of equations are

$$[\mathbf{A}\mathbf{X}_r]_{j\ell m} = [\mathbf{G}_X]_{j\ell m} + [\mathbf{G}_0]_{j\ell m} \quad \forall j, \ell, m$$

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where

- \mathbf{A} – $M(\ell_{\max} + 1)^2 \times M(\ell_{\max} + 1)^2$ matrix

$$[\mathbf{A}\mathbf{X}_r]_{j\ell m} = [\mathbf{X}_r]_{j\ell m} - \sum_{i \neq j} \sum_{\ell', m'} \left(\sum_{n=1}^{N_{\text{leb}}} \omega_n^{\text{leb}} \omega_{ji} (x_j + r_j s_n) \left(\frac{r_{ijn}}{r_i} \right)^{\ell'} Y_{\ell'}^{m'}(s_{ijn}) Y_{\ell}^m(s_n) \right) \times [\mathbf{X}_r]_{i\ell' m'}$$

- (r_{ijn}, s_{ijn}) – Spherical coordinates of $x_j + r_j s_n$ associated with Γ_i

$$x_j + r_j s_n = x_i + r_{ijn} s_{ijn} \quad \text{with} \quad s_{ijn} \in \mathbb{S}^2$$

- $[\mathbf{G}_X]_{jlm} = \sum_{n=1}^{N_{leb}} \omega_n^{leb} \chi_j^e(x_j + r_j s_n) \mathbf{g}(x_j + r_j s_n) \mathbf{Y}_\ell^m(s_n)$
- $[\mathbf{G}_0]_{jlm} = - \sum_{n=1}^{N_{leb}} \omega_n^{leb} \chi_j^e(x_j + r_j s_n) \psi_0(x_j + r_j s_n) \mathbf{Y}_\ell^m(s_n)$
- Similarly for the 2nd coupling equation

$$[\mathbf{B}\mathbf{X}_e]_{jlm} = [\mathbf{G}_X]_{jlm} \quad \forall j, \ell, m$$

- $[G_X]_{jlm} = \sum_{n=1}^{N_{leb}} \omega_n^{leb} \chi_j^e(x_j + r_j s_n) g(x_j + r_j s_n) Y_\ell^m(s_n)$
- $[G_0]_{jlm} = - \sum_{n=1}^{N_{leb}} \omega_n^{leb} \chi_j^e(x_j + r_j s_n) \psi_0(x_j + r_j s_n) Y_\ell^m(s_n)$
- Similarly for the 2nd coupling equation

$$[B X_e]_{jlm} = [G_X]_{jlm} \quad \forall j, \ell, m$$

where

○

$$\begin{aligned}
 [B X_e]_{jlm} &= [X_e]_{jlm} - \sum_{i \neq j} \sum_{\ell', m'} \\
 &\left(\sum_{n=1}^{N_{leb}} \omega_n^{leb} \omega_{ji}(x_j + r_j s_n) \left(\frac{i_{\ell'}(r_{ijn})}{i_{\ell'}(r_i)} \right) Y_{\ell'}^{m'}(s_{ijn}) Y_\ell^m(s_n) \right) \\
 &\times [X_e]_{i\ell'm'}
 \end{aligned}$$

- Linear System

$$LX = g,$$

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where

$$L = \begin{bmatrix} A & 0 \\ 0 & B \end{bmatrix}, \quad X = \begin{bmatrix} X_r \\ X_e \end{bmatrix}, \quad \text{and} \quad g = \begin{bmatrix} G_X + G_0 \\ G_X \end{bmatrix}$$

- Using definition of g

$$G_X = F_0 - C_1 X_r - C_2 X_e$$

- Linear System

$$\mathbf{L}X = g,$$

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- Using definition of g

$$\mathbf{G}_X = \mathbf{F}_0 - \mathbf{C}_1 X_r - \mathbf{C}_2 X_e$$

where

- \mathbf{F}_0 – Associated with $\partial_n \psi_0$
- \mathbf{C}_1 – Associated with $\partial_n \psi_r$
- \mathbf{C}_2 – Associated with $\partial_n \psi_e$

- Using the global strategy

$$\begin{bmatrix} \mathbf{A} & 0 \\ 0 & \mathbf{B} \end{bmatrix} \begin{bmatrix} \mathbf{X}_r^k \\ \mathbf{X}_e^k \end{bmatrix} = - \begin{bmatrix} \mathbf{C}_1 & \mathbf{C}_2 \\ \mathbf{C}_1 & \mathbf{C}_2 \end{bmatrix} \begin{bmatrix} \mathbf{X}_r^{k-1} \\ \mathbf{X}_e^{k-1} \end{bmatrix} + \begin{bmatrix} \mathbf{G}_0 + \mathbf{F}_0 \\ \mathbf{F}_0 \end{bmatrix}$$

where

- k – Iteration

- Using the global strategy

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where

- k – Iteration
- \mathbf{A} , \mathbf{B} are sparse
- \mathbf{C}_1 , \mathbf{C}_2 are not sparse

- Energy for LPB equations¹

$$E_s = \frac{1}{2} \langle \psi_r, \rho_M \rangle = \frac{1}{2} \sum_{j=1}^M \langle X, Q \rangle_j,$$

where,

$$[Q]_{j\ell} = \begin{cases} q_j \delta_{\ell 0}, & \text{if } 1 \leq j \leq M, \\ 0 & \text{if } M < j \leq 2M. \end{cases}$$

and

$$\langle X, Q \rangle_j = \sum_{\ell} [X]_{j\ell} [Q]_{j\ell}.$$

¹Fogolari, Brigo, Molinari: JMR 15, 2002

- Force with respect to λ

$$F_\lambda = \nabla^\lambda (E_s) = \frac{1}{2} \left(\langle \nabla^\lambda X, Q \rangle + \langle X, \nabla^\lambda Q \rangle \right) = \frac{1}{2} \langle \nabla^\lambda X, Q \rangle$$

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- $LX = g$ be the ddLPB system

$$\begin{aligned} \nabla^\lambda LX + L \nabla^\lambda X &= \nabla^\lambda g \\ \nabla^\lambda X &= L^{-1} \left(\nabla^\lambda g - \nabla^\lambda LX \right). \end{aligned}$$

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- Substituting $\nabla^\lambda X$

$$\begin{aligned} F_\lambda &= \frac{1}{2} \langle L^{-1} (\nabla^\lambda g - \nabla^\lambda LX), Q \rangle \\ &= \frac{1}{2} \langle (\nabla^\lambda g - \nabla^\lambda LX), (L^{-1})^* Q \rangle \\ &= \frac{1}{2} \langle (\nabla^\lambda g - \nabla^\lambda LX), X_{\text{adj}} \rangle \end{aligned}$$

- Accuracy of the Discretisation

¹ Mikhalev, Nottoli, Stamm: JCP : 157(11), 114103 , 2022

² Jurrus et. al. : Protein Sci. 27 (1), 112-128, 2018

³ Geng, Kransy: JCP, 247, 62-78, 2013

- Accuracy of the Discretisation
 - Analytical Forces vs Finite Difference

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 - Comparison with other software^{2,3}

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- Constants in the Model

- $\epsilon_1 = 1, \epsilon_2 = 78.54$

- $\kappa = 0.104 \text{ \AA}^{-1}$

¹Herbst, J., Lipparini, Mikhalev, Notolli, Stamm, ddX: <https://github.com/ddsolvation/ddX>

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 - Outer Tol= 10^{-8}
 - Inner Tol= 10^{-10}

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- Onthefly: Without storing the matrices
- Incore: Storing the matrices

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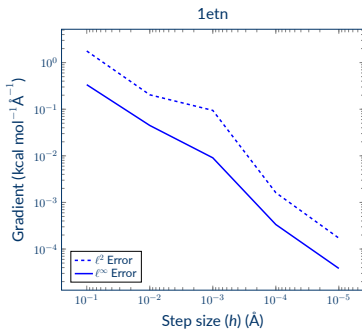
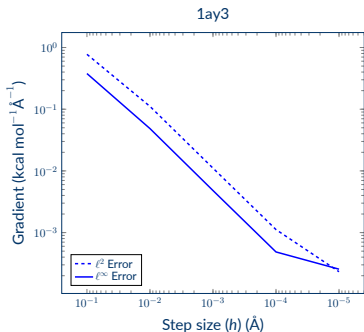
¹Herbst, J., Lipparini, Mikhalev, Notolli, Stamm, ddX: <https://github.com/ddSolvation/ddX>

- Test Structures²

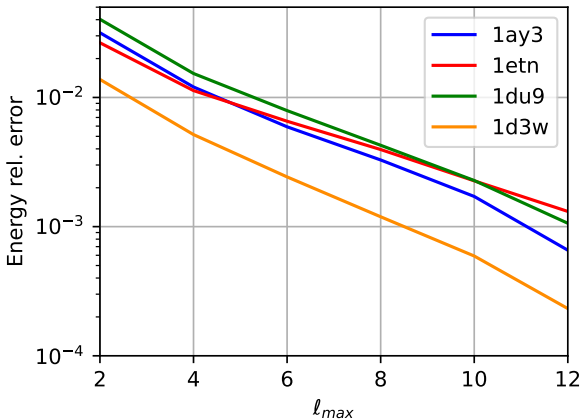
PDB Code	M	Name
1ay3	25	Nodularin
1etn	180	Enterotoxin
1du9	380	Scorpion toxin
1d3w	2049	Ferredoxin
1jvu	3964	Ribonuclease A
1qjt	9046	EH1 domain
1a3n	10087	Human haemoglobin
1ju2	20260	Hydroxynitrile lyase

²Berman et. al. : NAR 28, 235-242, 2000

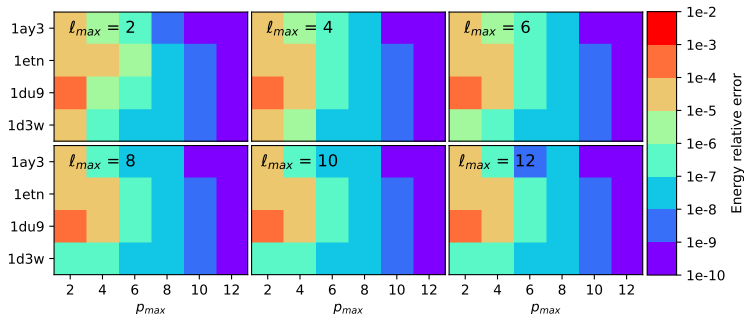
• Analytical Forces vs Finite Difference



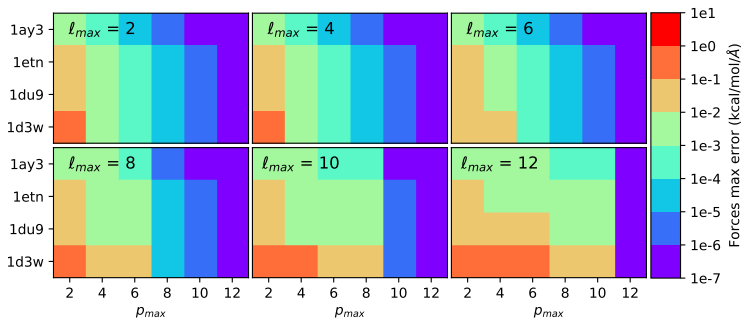
- Relative error of the Energy



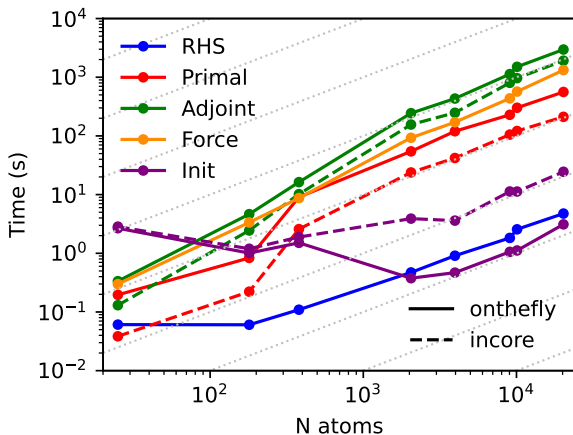
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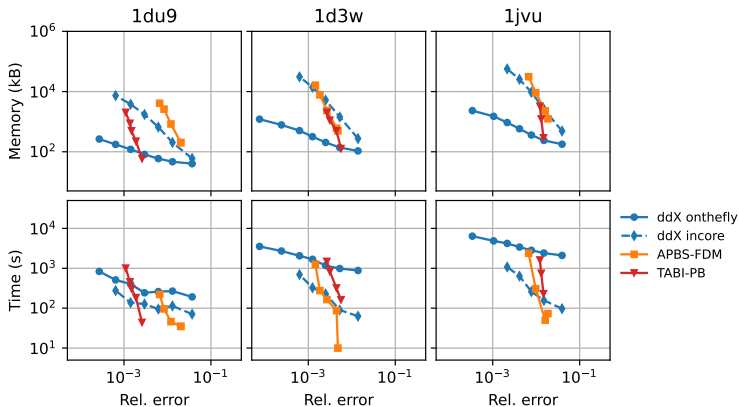
- Maximum Absolute error of the Forces



- Time and Memory for one ddLPB calculation



• Comparison with other Software



- **Conclusions**¹
 - **Formulation** of domain decomposition method for LPB equation²

¹ J., Nottoli, Mikhalev, Quan, Stamm: arXiv : 2203.00552 , 2022

² Quan, Stamm, Maday: SISC 41, B320–B350, 2019

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