# Domain Decomposition Methods for the Poisson-Boltzmann Equations

Abhinav Jha

Numerical Mathematics for High Performance Computing, Universität Stuttgart

Institute Seminar 24<sup>th</sup> October 2023

Joint work with B. Stamm (Universität Stuttgart, Stuttgart)





# Outline

- 1 Model Problem
- 2 ddPB Method
- 3 ddPB Derivation
- 4 Numerical Studies
- 5 Conclusions and Outlook





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

- Ionic Solvation Models<sup>1</sup>
  - Explicit Solvation Models
    - Adopts molecular representation of both solute and solvent
    - Accurate results
    - Computationally expensive

<sup>1</sup>Zhang et. al.: JCTC, 13, 1034-1043, 2017

<sup>2</sup>Cances, Mennucci, Tomasi: JCP 107 (8), 3032-3041, 1997

<sup>3</sup>Honig, Nicholls: Sci. 268, 1144-1149, 1995





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

- Ionic Solvation Models<sup>1</sup>
  - Explicit Solvation Models
    - Adopts molecular representation of both solute and solvent
    - Accurate results
    - Computationally expensive
  - Implicit Solvation Models <sup>2,3</sup>
    - Microscopic treatment of solute
    - Macroscopic treatment of solvent using physical properties
    - Less computational cost

<sup>1</sup>Zhang et. al.: JCTC, 13, 1034-1043, 2017

<sup>2</sup>Cances, Mennucci, Tomasi: JCP 107 (8), 3032-3041, 1997

<sup>3</sup>Honig, Nicholls: Sci. 268, 1144-1149, 1995





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outle
---



Figure 1: Formaldehyde Molecule





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• Poisson-Boltzman (PB) Equation <sup>1,2</sup>

$$-\nabla \cdot \left[\varepsilon_{\mathsf{abs}}\varepsilon(\mathbf{x})\nabla \tilde{\psi}(\mathbf{x})\right] = \rho^{\mathsf{sol}}(\mathbf{x}) + \rho^{\mathsf{ions}}(\mathbf{x}) \quad \text{in } \mathbb{R}^3$$

 $\circ \ ilde{\psi}(\mathbf{x})$  : Electrostatic potential

<sup>1</sup>Gouy: JPTA 9, 457-468, 1910 <sup>2</sup>Chapman: Journal of Science, 25, 475-481, 1913





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• Poisson-Boltzman (PB) Equation <sup>1,2</sup>

$$-\nabla \cdot \left[\varepsilon_{\mathsf{abs}}\varepsilon(\mathbf{x})\nabla \tilde{\psi}(\mathbf{x})\right] = \rho^{\mathsf{sol}}(\mathbf{x}) + \rho^{\mathsf{ions}}(\mathbf{x}) \quad \text{in } \mathbb{R}^3$$

 $\begin{array}{l} \circ ~~ \tilde{\psi}(\mathbf{x}): \text{Electrostatic potential} \\ \circ ~~ \varepsilon(\mathbf{x}): \text{Space-dependent dielectric permittivity} \\ \circ ~~ \rho^{\text{sol}}(\mathbf{x}): \text{Solute charge distribution} \end{array}$ 

$$\rho^{\rm sol}(\mathbf{x}) = \sum_{i=1}^{\sf M} q_i \delta(\mathbf{x} - \mathbf{x}_i)$$

- M : Number of solute atoms -  $q_i$  : Total charge on the  $i^{\text{th}}$  atom

<sup>1</sup>Gouy: JPTA 9, 457-468, 1910

<sup>2</sup>Chapman: Journal of Science, 25, 475-481, 1913





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

# $\circ \ \rho^{ions}(\mathbf{x})$ : lonic charge distribution

$$\rho^{\text{ions}}(\mathbf{x}) = \sum_{i=1}^{N_{\text{ions}}} z_i e \lambda(\mathbf{x}) c_i^{\infty} \exp\left(\frac{-z_i e \tilde{\psi}(\mathbf{x})}{K_{\text{B}} T}\right)$$

<sup>1</sup>Stein, Herbert, Head-Gordon: JCP, 151(22), 2019





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

 $\circ \ \rho^{ions}(\mathbf{x})$  : lonic charge distribution

$$\rho^{\text{ions}}(\mathbf{x}) = \sum_{i=1}^{N_{\text{ions}}} z_i e \lambda(\mathbf{x}) c_i^{\infty} \exp\left(\frac{-z_i e \tilde{\psi}(\mathbf{x})}{K_{\text{B}} T}\right)$$

• For 1:1 ionic solution<sup>1</sup>

$$ho^{
m ions}(\mathbf{x}) = -2ce\lambda(\mathbf{x})\sinh\left(rac{e ilde{\psi}(\mathbf{x})}{K_{
m B}T}
ight)$$

 $-\lambda(\mathbf{x})$ : Ion-exclusion function







Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• For 1:1 solution Poisson-Boltzman (PB) Equation

$$-\nabla \cdot \left[\varepsilon_{\mathsf{abs}}\varepsilon(\mathbf{x})\nabla \tilde{\psi}(\mathbf{x})\right] + 2ec\lambda(\mathbf{x})\sinh\left(\frac{e\tilde{\psi}(\mathbf{x})}{K_{\mathsf{B}}T}\right) = \rho^{\mathsf{sol}}(\mathbf{x}) \quad \text{in } \ \mathbb{R}^{3}$$

<sup>1</sup>Debye, Hückel: PZ 24(9), 185-206, 1923





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• For 1 : 1 solution Poisson-Boltzman (PB) Equation

$$-\nabla \cdot \left[\varepsilon_{\mathsf{abs}}\varepsilon(\mathbf{x})\nabla \tilde{\psi}(\mathbf{x})\right] + 2ec\lambda(\mathbf{x})\sinh\left(\frac{e\tilde{\psi}(\mathbf{x})}{\mathsf{K}_{\mathsf{B}}\mathsf{T}}\right) = \rho^{\mathsf{sol}}(\mathbf{x}) \quad \text{in } \ \mathbb{R}^{3}$$

• Dimensionless Poisson-Boltzman (PB) Equation

$$-\nabla \cdot [\varepsilon(\mathbf{x})\nabla\psi(\mathbf{x})] + \kappa^2 \varepsilon_{\rm s}\lambda(\mathbf{x})\sinh\left(\psi(\mathbf{x})\right) = \frac{1}{\beta\varepsilon_{\rm abs}}\rho^{\rm sol}(\mathbf{x}) \quad \text{in } \ \mathbb{R}^3$$

<sup>1</sup>Debye, Hückel: PZ 24(9), 185-206, 1923





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• For 1 : 1 solution Poisson-Boltzman (PB) Equation

$$-\nabla \cdot \left[\varepsilon_{\mathsf{abs}}\varepsilon(\mathbf{x})\nabla \tilde{\psi}(\mathbf{x})\right] + 2ec\lambda(\mathbf{x})\sinh\left(\frac{e\tilde{\psi}(\mathbf{x})}{K_{\mathsf{B}}\mathsf{T}}\right) = \rho^{\mathsf{sol}}(\mathbf{x}) \quad \text{in } \ \mathbb{R}^{3}$$

• Dimensionless Poisson-Boltzman (PB) Equation

$$-\nabla \cdot [\varepsilon(\mathbf{x})\nabla\psi(\mathbf{x})] + \kappa^2 \varepsilon_{s}\lambda(\mathbf{x})\sinh\left(\psi(\mathbf{x})\right) = \frac{1}{\beta\varepsilon_{\mathsf{abs}}}\rho^{\mathsf{sol}}(\mathbf{x}) \quad \text{in } \ \mathbb{R}^3$$

•  $\psi(\mathbf{x}) : \tilde{\psi}(\mathbf{x})\beta$ •  $\kappa$  : Debye Hückel Screening Constant <sup>1</sup> •  $\beta : e/K_{B}T$ 

<sup>1</sup>Debye, Hückel: PZ 24(9), 185-206, 1923





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook



Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook



Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook



Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook



Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook







# Permittivity and Ion-Exclusion Function

Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• Dielectric Permittivity Function<sup>1</sup>

$$\varepsilon(\mathbf{x}) = \begin{cases} 1 & \mathbf{x} \in \Omega_{\mathsf{SES}}, \\ 1 + (\varepsilon_{\mathsf{s}} - 1)\xi\left(\frac{f_{\mathsf{SAS}}(\mathbf{x}) + \mathbf{r}_{p} + a}{\mathbf{r}_{p} + a}\right) & \mathbf{x} \in \mathcal{L}_{\varepsilon}, \\ \varepsilon_{\mathsf{s}} & \mathsf{else}, \end{cases}$$

<sup>1</sup>Quan, Stamm: JCP, 322, 760-782, 2016 <sup>2</sup>Stern: ZFE, 30(21-22), 508, 1924





# Permittivity and Ion-Exclusion Function

Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• Dielectric Permittivity Function<sup>1</sup>

$$\varepsilon(\mathbf{x}) = \begin{cases} 1 & \mathbf{x} \in \Omega_{\mathsf{SES}}, \\ 1 + (\varepsilon_{\mathsf{s}} - 1)\xi\left(\frac{f_{\mathsf{SAS}}(\mathbf{x}) + \mathbf{r}_{p} + a}{\mathbf{r}_{p} + a}\right) & \mathbf{x} \in \mathcal{L}_{\varepsilon}, \\ \varepsilon_{\mathsf{s}} & \mathsf{else}, \end{cases}$$

Ion-Exclusion Function<sup>2</sup>

$$\lambda(\mathbf{x}) = \begin{cases} 0 & \mathbf{x} \in \Omega_{\mathsf{SES}-\mathsf{S}}, \\ \xi\left(\frac{\mathsf{f}_{\mathsf{SAS}}(\mathbf{x}) + \mathsf{r}_p}{\mathsf{r}_p + a}\right) & \mathbf{x} \in \mathcal{L}_\lambda, \\ 1 & \text{else}, \end{cases}$$

<sup>1</sup>Quan, Stamm: JCP, 322, 760-782, 2016 <sup>2</sup>Stern: ZFE, 30(21-22), 508, 1924





# Permittivity and Ion-Exclusion Function

Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook



Linearity in Different Regions

- C: Constant, NC: Non-Constant
- L: Linear, NL: Non-Linear





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• The PB equation can be written in two equations

$$\begin{split} -\nabla \cdot \left[ \varepsilon(\mathbf{x}) \nabla \psi(\mathbf{x}) \right] + \kappa^2 \varepsilon_s \lambda(\mathbf{x}) \sinh \left( \psi(\mathbf{x}) \right) &= \quad \frac{1}{\beta \varepsilon_{\text{abs}}} \rho^{\text{sol}}(\mathbf{x}) \qquad \text{in } \Omega_0, \\ -\Delta \psi(\mathbf{x}) + \kappa^2 \psi(\mathbf{x}) &= \quad 0 \qquad \qquad \text{in } \Omega_\infty, \end{split}$$

with

$$\begin{bmatrix} \boldsymbol{\psi} \end{bmatrix} = 0,$$
  
$$\begin{bmatrix} \partial_{\mathbf{n}} \boldsymbol{\psi} \end{bmatrix} = 0 \quad \text{on} \quad \Gamma_0 := \partial \Omega_0,$$





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• Using Potential Theory the final equations are

$$\begin{aligned} -\nabla \cdot \left[ \varepsilon(\mathbf{x}) \nabla \psi_{\mathbf{r}}(\mathbf{x}) \right] + \kappa^2 \varepsilon_{\mathbf{s}} \lambda(\mathbf{x}) \mathcal{F} \left( \psi_{\mathbf{r}} + \psi_0 \right) \left( \psi_{\mathbf{r}} + \psi_0 \right) \left( \mathbf{x} \right) \\ = \nabla \cdot \left[ \left( \varepsilon(\mathbf{x}) - 1 \right) \nabla \psi_0(\mathbf{x}) \right] & \text{in } \Omega_0 \quad [\mathsf{GSP}] \end{aligned}$$





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• Using Potential Theory the final equations are

$$\begin{aligned} -\nabla \cdot \left[ \varepsilon(\mathbf{x}) \nabla \psi_{\mathsf{r}}(\mathbf{x}) \right] + \kappa^{2} \varepsilon_{\mathsf{s}} \lambda(\mathbf{x}) \mathcal{F} \left( \psi_{\mathsf{r}} + \psi_{0} \right) \left( \psi_{\mathsf{r}} + \psi_{0} \right) \left( \mathbf{x} \right) \\ = \nabla \cdot \left[ \left( \varepsilon(\mathbf{x}) - 1 \right) \nabla \psi_{0}(\mathbf{x}) \right] & \text{in } \Omega_{0} \quad [\mathsf{GSP}] \end{aligned}$$

$$-\Delta\psi_{\mathsf{e}}(\mathbf{x}) + \kappa^{2}\psi_{\mathsf{e}}(\mathbf{x}) = 0 \quad \text{in } \Omega_{0} \quad [\mathsf{HSP}]$$





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• Using Potential Theory the final equations are

$$\begin{aligned} -\nabla \cdot \left[ \varepsilon(\mathbf{x}) \nabla \psi_{\mathbf{r}}(\mathbf{x}) \right] + \kappa^2 \varepsilon_{\mathbf{s}} \lambda(\mathbf{x}) \mathcal{F} \left( \psi_{\mathbf{r}} + \psi_0 \right) \left( \psi_{\mathbf{r}} + \psi_0 \right) \left( \mathbf{x} \right) \\ = \nabla \cdot \left[ \left( \varepsilon(\mathbf{x}) - 1 \right) \nabla \psi_0(\mathbf{x}) \right] & \text{in } \Omega_0 \quad \text{[GSP]} \end{aligned}$$

$$-\Delta\psi_{\mathsf{e}}(\mathbf{x}) + \kappa^{2}\psi_{\mathsf{e}}(\mathbf{x}) = 0 \quad \text{in } \Omega_{0} \quad [\mathsf{HSP}]$$

with

$$\begin{split} \psi_0 + \psi_{\mathsf{r}} &= \psi_{\mathsf{e}} \quad \text{on } \Gamma_0, \\ \psi_{\mathsf{e}} &= \mathbf{S}_{\kappa} \sigma_{\mathsf{e}} \qquad \text{on } \Gamma_0 \end{split}$$





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• Using Potential Theory the final equations are

$$\begin{aligned} -\nabla \cdot \left[ \varepsilon(\mathbf{x}) \nabla \psi_{\mathbf{r}}(\mathbf{x}) \right] + \kappa^2 \varepsilon_{\mathbf{s}} \lambda(\mathbf{x}) \mathcal{F} \left( \psi_{\mathbf{r}} + \psi_0 \right) \left( \psi_{\mathbf{r}} + \psi_0 \right) \left( \mathbf{x} \right) \\ = \nabla \cdot \left[ \left( \varepsilon(\mathbf{x}) - 1 \right) \nabla \psi_0(\mathbf{x}) \right] & \text{in } \Omega_0 \quad \text{[GSP]} \end{aligned}$$

$$-\Delta\psi_{\mathsf{e}}(\mathbf{x}) + \kappa^{2}\psi_{\mathsf{e}}(\mathbf{x}) = 0 \quad \text{in } \Omega_{0} \quad [\mathsf{HSP}]$$

with

$$\begin{split} \psi_0 + \psi_{\mathsf{r}} &= \psi_{\mathsf{e}} \quad \text{on } \Gamma_0, \\ \psi_{\mathsf{e}} &= \mathbf{S}_{\kappa} \sigma_{\mathsf{e}} \qquad \text{on } \Gamma_0 \end{split}$$

#### where

- $\circ \ \psi_{\mathbf{r}}$  : Reaction potential in  $\Omega$
- $\circ \ \psi_0$  : Potential generated by  $\rho_{\mathsf{M}}$  satisfying,

$$-\Delta\psi_0 = \frac{1}{\beta\varepsilon_{\rm abs}}\rho_{\rm M}$$





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

# $\circ \ \psi_{\mathsf{e}}$ : Extended potential from $\Omega^{\mathsf{C}}$ to $\Omega^{0}$

<sup>1</sup>Sauter, Schwab, Springer, Berlin-2011, 101-181





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

•  $\psi_{e}$ : Extended potential from  $\Omega^{C}$  to  $\Omega^{0}$ •  $\mathcal{F}(\Phi) = \frac{\sinh(\Phi)}{\Phi}$ 

<sup>1</sup>Sauter, Schwab, Springer, Berlin-2011, 101-181





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• 
$$\psi_{e}$$
 : Extended potential from  $\Omega^{C}$  to  $\Omega^{0}$   
•  $\mathcal{F}(\Phi) = \frac{\sinh(\Phi)}{\Phi}$   
•  $\sigma_{e}$  : Charge density generating  $\psi_{e}$  satisfying

$$\mathbf{S}_{\kappa}\boldsymbol{\sigma}_{\mathbf{e}}(\mathbf{x}) = \int_{\Gamma_0} \frac{\exp\left(-\kappa |\mathbf{x} - \mathbf{y}|\right)\boldsymbol{\sigma}_{\mathbf{e}}(\mathbf{y})}{4\pi |\mathbf{x} - \mathbf{y}|} = \psi_{\mathbf{e}} \quad \forall \ \mathbf{x} \in \Gamma_0$$

 $\circ~{\rm S}_{\kappa}$  : Invertible single-layer potential operator ^1

 $\mathbf{S}_{\boldsymbol{\kappa}}: \mathbf{H}^{-1/2}(\Gamma_0) \to \mathbf{H}^{1/2}(\Gamma_0)$ 

<sup>1</sup>Sauter, Schwab, Springer, Berlin-2011, 101-181





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook







12

Model Problem ddPB Method ddPB Derivation Nun	erical Studies Conclusions and Outlook
---	--







Model Problem ddPB Method ddPB Derivation Nun	erical Studies Conclusions and Outlook
---	--







Model Problem ddPB Method ddPB Derivation	Numerical Studies		
---	-------------------	--	--







Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• We can decompose  $\Omega_0$ 

$$\Omega_0 = \bigcup_{j=1}^{\mathsf{M}} \Omega_j, \qquad \Omega_j = \mathsf{B}_{\mathsf{R}_j}(\mathbf{x}_j)$$

 $\circ \ \mathbf{R}_{\mathbf{j}} = \mathbf{r}_{\mathbf{j}} + \mathbf{a} + \mathbf{r}_0 + \mathbf{r}_{\mathbf{p}}$ 

- <sup>5</sup>Gatto, Lipparini, Stamm: JCP 147, 224108, 2017
- <sup>6</sup>Quan, Stamm, Maday: SISC 41(2), B320-B350, 2019
- <sup>7</sup> J., Nottoli, Mikhalev, Quan, Stamm: JCP 158, 104105, 2023

<sup>8</sup>Nottoli, Herbst, J., Lipparini, Mikhalev, Stamm: ddX: https://github.com/ddsolvation/ddX





<sup>&</sup>lt;sup>1</sup>Cances, Maday, Stamm: JCP 139(5), 054111, 2013

<sup>&</sup>lt;sup>2</sup>Lipparini, Stamm, Cances, Maday, Mennucci: JCTC 9(8), 3637-3648, 2013

<sup>&</sup>lt;sup>3</sup>Lipparini, et.al.: JPCL 5(4), 953-958, 2014

<sup>&</sup>lt;sup>4</sup>Stamm, Cances, Lipparini, Maday: JCP 144, 054101, 2016

Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• We can decompose Ω<sub>0</sub>

$$\Omega_0 = \bigcup_{j=1}^{\mathsf{M}} \Omega_j, \qquad \Omega_j = \mathsf{B}_{\mathsf{R}_j}(\mathbf{x}_j)$$

- $\circ \ \mathbf{R}_{\mathbf{j}} = \mathbf{r}_{\mathbf{j}} + \mathbf{a} + \mathbf{r}_0 + \mathbf{r}_{\mathbf{p}}$
- History of dd-methods
  - ddCOSMO: COnductor-like Screening MOdel<sup>1,2,3</sup>

- <sup>5</sup>Gatto, Lipparini, Stamm: JCP 147, 224108, 2017
- <sup>6</sup>Quan, Stamm, Maday: SISC 41(2), B320-B350, 2019
- <sup>7</sup> J., Nottoli, Mikhalev, Quan, Stamm: JCP 158, 104105, 2023

<sup>8</sup>Nottoli, Herbst, J., Lipparini, Mikhalev, Stamm: ddX: https://github.com/ddsolvation/ddX





<sup>&</sup>lt;sup>1</sup>Cances, Maday, Stamm: JCP 139(5), 054111, 2013

<sup>&</sup>lt;sup>2</sup>Lipparini, Stamm, Cances, Maday, Mennucci: JCTC 9(8), 3637-3648, 2013

<sup>&</sup>lt;sup>3</sup>Lipparini, et.al.: JPCL 5(4), 953-958, 2014

<sup>&</sup>lt;sup>4</sup>Stamm, Cances, Lipparini, Maday: JCP 144, 054101, 2016

Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• We can decompose  $\Omega_0$ 

$$\Omega_0 = \bigcup_{j=1}^{\mathsf{M}} \Omega_j, \qquad \Omega_j = \mathsf{B}_{\mathsf{R}_j}(\mathsf{x}_j)$$

- $\circ \ \mathbf{R}_{\mathbf{j}} = \mathbf{r}_{\mathbf{j}} + \mathbf{a} + \mathbf{r}_0 + \mathbf{r}_{\mathbf{p}}$
- History of dd-methods
  - ddCOSMO: COnductor-like Screening MOdel<sup>1,2,3</sup>
  - ddPCM: Polarizable Continuum Model<sup>4,5</sup>

- <sup>4</sup>Stamm, Cances, Lipparini, Maday: JCP 144, 054101, 2016
- <sup>5</sup>Gatto, Lipparini, Stamm: JCP 147, 224108, 2017
- <sup>6</sup>Quan, Stamm, Maday: SISC 41(2), B320-B350, 2019
- <sup>7</sup> J., Nottoli, Mikhalev, Quan, Stamm: JCP 158, 104105, 2023

<sup>8</sup>Nottoli, Herbst, J., Lipparini, Mikhalev, Stamm: ddX: https://github.com/ddsolvation/ddX





<sup>&</sup>lt;sup>1</sup>Cances, Maday, Stamm: JCP 139(5), 054111, 2013

<sup>&</sup>lt;sup>2</sup>Lipparini, Stamm, Cances, Maday, Mennucci: JCTC 9(8), 3637-3648, 2013

<sup>&</sup>lt;sup>3</sup>Lipparini, et.al.: JPCL 5(4), 953-958, 2014

Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• We can decompose  $\Omega_0$ 

$$\Omega_0 = \bigcup_{j=1}^{\mathsf{M}} \Omega_j, \qquad \Omega_j = \mathsf{B}_{\mathsf{R}_j}(\mathbf{x}_j)$$

- $\circ \ \mathbf{R}_{\mathbf{j}} = \mathbf{r}_{\mathbf{j}} + \mathbf{a} + \mathbf{r}_0 + \mathbf{r}_{\mathbf{p}}$
- History of dd-methods
  - ddCOSMO: COnductor-like Screening MOdel<sup>1,2,3</sup>
  - ddPCM: Polarizable Continuum Model<sup>4,5</sup>
  - ddLPB: Linear Poisson-Boltzmann<sup>6,7</sup>

- <sup>4</sup>Stamm, Cances, Lipparini, Maday: JCP 144, 054101, 2016
- <sup>5</sup>Gatto, Lipparini, Stamm: JCP 147, 224108, 2017
- <sup>6</sup>Quan, Stamm, Maday: SISC 41(2), B320-B350, 2019
- <sup>7</sup> J., Nottoli, Mikhalev, Quan, Stamm: JCP 158, 104105, 2023
- <sup>8</sup>Nottoli, Herbst, J., Lipparini, Mikhalev, Stamm: ddX: https://github.com/ddsolvation/ddX





<sup>&</sup>lt;sup>1</sup>Cances, Maday, Stamm: JCP 139(5), 054111, 2013

<sup>&</sup>lt;sup>2</sup>Lipparini, Stamm, Cances, Maday, Mennucci: JCTC 9(8), 3637-3648, 2013

<sup>&</sup>lt;sup>3</sup>Lipparini, et.al.: JPCL 5(4), 953-958, 2014
#### ddPB-Method

Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• We can decompose Ω<sub>0</sub>

$$\Omega_0 = \bigcup_{j=1}^{\mathsf{M}} \Omega_j, \qquad \Omega_j = \mathsf{B}_{\mathsf{R}_j}(\mathbf{x}_j)$$

- $\circ \ \mathbf{R}_{\mathbf{j}} = \mathbf{r}_{\mathbf{j}} + \mathbf{a} + \mathbf{r}_0 + \mathbf{r}_{\mathbf{p}}$
- History of dd-methods
  - ddCOSMO: COnductor-like Screening MOdel<sup>1,2,3</sup>
  - ddPCM: Polarizable Continuum Model<sup>4,5</sup>
  - ddLPB: Linear Poisson-Boltzmann<sup>6,7</sup>
  - ddX<sup>8</sup>

<sup>1</sup>Cances, Maday, Stamm: JCP 139(5), 054111, 2013

<sup>2</sup>Lipparini, Stamm, Cances, Maday, Mennucci: JCTC 9(8), 3637-3648, 2013

<sup>3</sup>Lipparini, et.al.: JPCL 5(4), 953-958, 2014

<sup>4</sup>Stamm, Cances, Lipparini, Maday: JCP 144, 054101, 2016

<sup>5</sup>Gatto, Lipparini, Stamm: JCP 147, 224108, 2017

<sup>6</sup>Quan, Stamm, Maday: SISC 41(2), B320-B350, 2019

<sup>7</sup> J., Nottoli, Mikhalev, Quan, Stamm: JCP 158, 104105, 2023

<sup>8</sup>Nottoli, Herbst, J., Lipparini, Mikhalev, Stamm: ddX: https://github.com/ddsolvation/ddX





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• GSP equation in unit ball

$$\begin{split} -\nabla \cdot \left[ \tilde{\varepsilon}(\mathbf{x}) \nabla u(\mathbf{x}) \right] + \tilde{\lambda}(\mathbf{x}) \tilde{\mathcal{F}} \left( \overline{u}(\mathbf{x}) \right) u(\mathbf{x}) &= f(\mathbf{x}) \quad \text{in } B_1(\mathbf{0}) \\ u(\mathbf{x}) &= \phi_r(\mathbf{x}) \quad \text{on } \partial B_1(\mathbf{0}) \end{split}$$





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• GSP equation in unit ball

$$\begin{aligned} -\nabla \cdot \left[ \tilde{\varepsilon}(\mathbf{x}) \nabla u(\mathbf{x}) \right] + \tilde{\lambda}(\mathbf{x}) \tilde{\mathcal{F}} \left( \overline{u}(\mathbf{x}) \right) u(\mathbf{x}) &= f(\mathbf{x}) \quad \text{in } B_1(\mathbf{0}) \\ u(\mathbf{x}) &= \phi_r(\mathbf{x}) \quad \text{on } \partial B_1(\mathbf{0}) \end{aligned}$$

• Transformation to Homogeneous Problem

$$\begin{aligned} -\nabla \cdot \left[ \tilde{\varepsilon}(\mathbf{x}) \nabla \mathbf{w}(\mathbf{x}) \right] + \tilde{\lambda}(\mathbf{x}) \tilde{\mathcal{F}} \left( \left( \overline{\mathbf{w} + \hat{u}_1} \right)(\mathbf{x}) \right) \mathbf{w}(\mathbf{x}) &= \tilde{f}(\mathbf{x}), \quad \text{ in } B_1(\mathbf{0}) \\ \mathbf{w}(\mathbf{x}) &= 0 \quad \text{ on } \partial B_1(\mathbf{0}), \end{aligned}$$





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• GSP equation in unit ball

$$\begin{aligned} -\nabla \cdot \left[\tilde{\varepsilon}(\mathbf{x}) \nabla u(\mathbf{x})\right] + \tilde{\lambda}(\mathbf{x}) \tilde{\mathcal{F}}\left(\overline{u}(\mathbf{x})\right) u(\mathbf{x}) &= f(\mathbf{x}) \quad \text{in } B_1(\mathbf{0}) \\ u(\mathbf{x}) &= \phi_r(\mathbf{x}) \quad \text{on } \partial B_1(\mathbf{0}) \end{aligned}$$

• Transformation to Homogeneous Problem

$$\begin{aligned} -\nabla \cdot \left[\tilde{\varepsilon}(\mathbf{x})\nabla \mathbf{w}(\mathbf{x})\right] + \tilde{\lambda}(\mathbf{x})\tilde{\mathcal{F}}\left(\left(\overline{\mathbf{w} + \hat{u}_1}\right)(\mathbf{x})\right)\mathbf{w}(\mathbf{x}) &= \tilde{f}(\mathbf{x}), \quad \text{ in } B_1(\mathbf{0})\\ \mathbf{w}(\mathbf{x}) &= 0 \quad \text{ on } \partial B_1(\mathbf{0}), \end{aligned}$$

$$\circ \mathbf{w}(\mathbf{x}) = \mathbf{u}(\mathbf{x}) - \hat{u}_1(\mathbf{x})$$
  
 
$$\circ \tilde{\mathbf{f}}(\mathbf{x}) = \mathbf{f}(\mathbf{x}) + \nabla \cdot [\tilde{\varepsilon}(\mathbf{x})\nabla \hat{u}_1(\mathbf{x})] - \tilde{\lambda}(\mathbf{x})\tilde{\mathcal{F}}\left(\left(\overline{\mathbf{w} + \hat{u}_1}\right)(\mathbf{x})\right) \hat{u}_1(\mathbf{x})$$





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• GSP equation in unit ball

$$\begin{aligned} -\nabla \cdot \left[\tilde{\varepsilon}(\mathbf{x}) \nabla u(\mathbf{x})\right] + \tilde{\lambda}(\mathbf{x}) \tilde{\mathcal{F}}\left(\overline{u}(\mathbf{x})\right) u(\mathbf{x}) &= f(\mathbf{x}) \quad \text{in } B_1(\mathbf{0}) \\ u(\mathbf{x}) &= \phi_r(\mathbf{x}) \quad \text{on } \partial B_1(\mathbf{0}) \end{aligned}$$

• Transformation to Homogeneous Problem

$$\begin{aligned} -\nabla \cdot \left[\tilde{\varepsilon}(\mathbf{x})\nabla \mathbf{w}(\mathbf{x})\right] + \tilde{\lambda}(\mathbf{x})\tilde{\mathcal{F}}\left(\left(\overline{\mathbf{w} + \hat{u}_1}\right)(\mathbf{x})\right)\mathbf{w}(\mathbf{x}) &= \tilde{f}(\mathbf{x}), \quad \text{ in } B_1(\mathbf{0})\\ \mathbf{w}(\mathbf{x}) &= 0 \quad \text{ on } \partial B_1(\mathbf{0}), \end{aligned}$$

 $\circ \mathbf{w}(\mathbf{x}) = \mathbf{u}(\mathbf{x}) - \hat{u}_1(\mathbf{x}) \\ \circ \tilde{f}(\mathbf{x}) = f(\mathbf{x}) + \nabla \cdot [\tilde{\varepsilon}(\mathbf{x})\nabla \hat{u}_1(\mathbf{x})] - \tilde{\lambda}(\mathbf{x})\tilde{\mathcal{F}}\left(\left(\overline{\mathbf{w} + \hat{u}_1}\right)(\mathbf{x})\right) \hat{u}_1(\mathbf{x}) \\ \circ \hat{u}_1(\mathbf{x}) : \text{Laplace solution satisfying the boundary condition}$ 





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• GSP equation in unit ball

$$\begin{aligned} -\nabla \cdot \left[\tilde{\varepsilon}(\mathbf{x}) \nabla u(\mathbf{x})\right] + \tilde{\lambda}(\mathbf{x}) \tilde{\mathcal{F}}\left(\overline{u}(\mathbf{x})\right) u(\mathbf{x}) &= f(\mathbf{x}) \quad \text{in } B_1(\mathbf{0}) \\ u(\mathbf{x}) &= \phi_r(\mathbf{x}) \quad \text{on } \partial B_1(\mathbf{0}) \end{aligned}$$

• Transformation to Homogeneous Problem

$$\begin{aligned} -\nabla \cdot \left[\tilde{\varepsilon}(\mathbf{x})\nabla \mathbf{w}(\mathbf{x})\right] + \tilde{\lambda}(\mathbf{x})\tilde{\mathcal{F}}\left(\left(\overline{\mathbf{w} + \hat{u}_1}\right)(\mathbf{x})\right)\mathbf{w}(\mathbf{x}) &= \tilde{f}(\mathbf{x}), \quad \text{ in } B_1(\mathbf{0})\\ \mathbf{w}(\mathbf{x}) &= 0 \quad \text{ on } \partial B_1(\mathbf{0}), \end{aligned}$$

 $\begin{array}{l} \circ \ \mathbf{w}(\mathbf{x}) = \mathbf{u}(\mathbf{x}) - \hat{u}_{1}(\mathbf{x}) \\ \circ \ \tilde{f}(\mathbf{x}) = f(\mathbf{x}) + \nabla \cdot [\tilde{\varepsilon}(\mathbf{x})\nabla \hat{u}_{1}(\mathbf{x})] - \tilde{\lambda}(\mathbf{x})\tilde{\mathcal{F}}\left(\left(\overline{\mathbf{w} + \hat{u}_{1}}\right)(\mathbf{x})\right) \hat{u}_{1}(\mathbf{x}) \\ \circ \ \hat{u}_{1}(\mathbf{x}) : \text{Laplace solution satisfying the boundary condition} \\ \bullet \ B_{r_{i}}(\mathbf{x}_{j}) \subset \Omega_{j} \end{array}$ 





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• GSP equation in unit ball

$$\begin{aligned} -\nabla \cdot \left[\tilde{\varepsilon}(\mathbf{x}) \nabla u(\mathbf{x})\right] + \tilde{\lambda}(\mathbf{x}) \tilde{\mathcal{F}}\left(\overline{u}(\mathbf{x})\right) u(\mathbf{x}) &= f(\mathbf{x}) \quad \text{in } B_1(\mathbf{0}) \\ u(\mathbf{x}) &= \phi_r(\mathbf{x}) \quad \text{on } \partial B_1(\mathbf{0}) \end{aligned}$$

• Transformation to Homogeneous Problem

$$\begin{aligned} -\nabla \cdot \left[\tilde{\varepsilon}(\mathbf{x})\nabla \mathbf{w}(\mathbf{x})\right] + \tilde{\lambda}(\mathbf{x})\tilde{\mathcal{F}}\left(\left(\overline{\mathbf{w} + \hat{u}_1}\right)(\mathbf{x})\right)\mathbf{w}(\mathbf{x}) &= \tilde{f}(\mathbf{x}), \quad \text{ in } B_1(\mathbf{0})\\ \mathbf{w}(\mathbf{x}) &= 0 \quad \text{ on } \partial B_1(\mathbf{0}), \end{aligned}$$

- $\circ \mathbf{w}(\mathbf{x}) = \mathbf{u}(\mathbf{x}) \hat{u}_{1}(\mathbf{x})$  $\circ \tilde{\mathbf{f}}(\mathbf{x}) = \mathbf{f}(\mathbf{x}) + \nabla \cdot [\tilde{\varepsilon}(\mathbf{x})\nabla\hat{u}_{1}(\mathbf{x})] - \tilde{\lambda}(\mathbf{x})\tilde{\mathcal{F}}\left(\left(\overline{\mathbf{w} + \hat{u}_{1}}\right)(\mathbf{x})\right)\hat{u}_{1}(\mathbf{x})$
- $\hat{u}_1(\mathbf{x})$  : Laplace solution satisfying the boundary condition
- $B_{\mathbf{r}_j}(\mathbf{x}_j) \subset \Omega_j$ 
  - $\psi_{\mathbf{r}}(\mathbf{x})$  is harmonic in  $B_{\mathbf{r}_j}(\mathbf{x}_j)$





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• GSP equation in unit ball

$$\begin{aligned} -\nabla \cdot \left[\tilde{\varepsilon}(\mathbf{x}) \nabla u(\mathbf{x})\right] + \tilde{\lambda}(\mathbf{x}) \tilde{\mathcal{F}}\left(\overline{u}(\mathbf{x})\right) u(\mathbf{x}) &= f(\mathbf{x}) \quad \text{in } B_1(\mathbf{0}) \\ u(\mathbf{x}) &= \phi_r(\mathbf{x}) \quad \text{on } \partial B_1(\mathbf{0}) \end{aligned}$$

• Transformation to Homogeneous Problem

$$\begin{aligned} -\nabla \cdot \left[\tilde{\varepsilon}(\mathbf{x})\nabla \mathbf{w}(\mathbf{x})\right] + \tilde{\lambda}(\mathbf{x})\tilde{\mathcal{F}}\left(\left(\overline{\mathbf{w} + \hat{u}_1}\right)(\mathbf{x})\right)\mathbf{w}(\mathbf{x}) &= \tilde{f}(\mathbf{x}), \quad \text{ in } B_1(\mathbf{0})\\ \mathbf{w}(\mathbf{x}) &= 0 \quad \text{ on } \partial B_1(\mathbf{0}), \end{aligned}$$

- $\circ \mathbf{w}(\mathbf{x}) = \mathbf{u}(\mathbf{x}) \hat{u}_{1}(\mathbf{x})$  $\circ \tilde{\mathbf{f}}(\mathbf{x}) = \mathbf{f}(\mathbf{x}) + \nabla \cdot \left[\tilde{\varepsilon}(\mathbf{x})\nabla\hat{u}_{1}(\mathbf{x})\right] - \tilde{\lambda}(\mathbf{x})\tilde{\mathcal{F}}\left(\left(\overline{\mathbf{w} + \hat{u}_{1}}\right)(\mathbf{x})\right)\hat{u}_{1}(\mathbf{x})$
- $\hat{u}_1(\mathbf{x})$  : Laplace solution satisfying the boundary condition
- $B_{\mathbf{r}_j}(\mathbf{x}_j) \subset \Omega_j$ 
  - $\psi_{\mathbf{r}}(\mathbf{x})$  is harmonic in  $B_{\mathbf{r}_i}(\mathbf{x}_j)$
  - $\mathbf{w}(\mathbf{x})$  is harmonic in  $B_{\delta}(\mathbf{0})$  where

$$\delta = \frac{\mathbf{r}_j}{\mathbf{r}_j + \mathbf{r}_0 + \mathbf{r}_p + a} \in (0, 1)$$





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• Find  $\mathbf{w} \in H^1_{0,\delta}(\mathcal{D})$  such that

$$\begin{split} \int_{\mathcal{D}} \tilde{\varepsilon}(\mathbf{x}) \nabla w(\mathbf{x}) \nabla \tilde{w}(\mathbf{x}) &+ \int_{\mathcal{D}} \tilde{\lambda}(\mathbf{x}) \tilde{\mathcal{F}}\left(\overline{w}(\mathbf{x})\right) w(\mathbf{x}) \tilde{w}(\mathbf{x}) \\ &+ \int_{\partial \mathsf{B}_{\delta}(\mathbf{0})} \left(\mathcal{T}w\right) \tilde{w}(\mathbf{x}) = \int_{\mathcal{D}} \tilde{f}(\mathbf{x}) \tilde{w}(\mathbf{x}) \quad \forall \ \tilde{w} \in H^{1}_{0,\delta}(\mathcal{D}), \end{split}$$





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• Find  $\mathbf{w} \in H^1_{0,\delta}(\mathcal{D})$  such that

$$\begin{split} \int_{\mathcal{D}} \tilde{\varepsilon}(\mathbf{x}) \nabla \mathbf{w}(\mathbf{x}) \nabla \tilde{w}(\mathbf{x}) &+ \int_{\mathcal{D}} \tilde{\lambda}(\mathbf{x}) \tilde{\mathcal{F}}(\overline{\mathbf{w}}(\mathbf{x})) \, \mathbf{w}(\mathbf{x}) \tilde{w}(\mathbf{x}) \\ &+ \int_{\partial B_{\delta}(\mathbf{0})} \left( \mathcal{T} \mathbf{w} \right) \tilde{w}(\mathbf{x}) = \int_{\mathcal{D}} \tilde{\mathbf{f}}(\mathbf{x}) \tilde{w}(\mathbf{x}) \quad \forall \ \tilde{w} \in H^{1}_{0,\delta}(\mathcal{D}), \end{split}$$

$$\circ \ \mathcal{D} = \mathsf{B}_1(\mathbf{0}) \setminus \mathsf{B}_{\delta}(\mathbf{0}) \\ \circ \ \mathsf{H}_{0,\delta}^1(\mathcal{D}) = \left\{ \mathsf{w} \in \mathsf{H}^1(\mathcal{D}) : \mathsf{w}|_{\partial \mathsf{B}_1(\mathbf{0})} = 0 \right\}$$





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• Find  $\mathbf{w} \in H^1_{0,\delta}(\mathcal{D})$  such that

$$\begin{split} \int_{\mathcal{D}} \tilde{\varepsilon}(\mathbf{x}) \nabla \mathbf{w}(\mathbf{x}) \nabla \tilde{w}(\mathbf{x}) &+ \int_{\mathcal{D}} \tilde{\lambda}(\mathbf{x}) \tilde{\mathcal{F}}\left(\overline{\mathbf{w}}(\mathbf{x})\right) \mathbf{w}(\mathbf{x}) \tilde{w}(\mathbf{x}) \\ &+ \int_{\partial \mathcal{B}_{\delta}(\mathbf{0})} \left(\mathcal{T}\mathbf{w}\right) \tilde{w}(\mathbf{x}) = \int_{\mathcal{D}} \tilde{\mathbf{f}}(\mathbf{x}) \tilde{w}(\mathbf{x}) \quad \forall \ \tilde{w} \in H^{1}_{0,\delta}(\mathcal{D}), \end{split}$$

$$\circ \ \begin{array}{l} \mathcal{D} = \mathcal{B}_1(\mathbf{0}) \setminus \mathcal{B}_{\delta}(\mathbf{0}) \\ \circ \ \mathcal{H}_{0,\delta}^1(\mathcal{D}) = \left\{ \mathbf{w} \in \mathcal{H}^1(\mathcal{D}) : \mathbf{w}|_{\partial \mathcal{B}_1(\mathbf{0})} = 0 \right\} \end{array}$$

Using Galerkin discretisation

$$\mathsf{w}_{\mathcal{B}}(\mathbf{r},\theta,\varphi) = \sum_{\mathbf{i}=0}^{\mathsf{N}} \sum_{\ell=0}^{\ell_{\max}} \sum_{\mathbf{m}=-\ell}^{\ell} [\phi_{\mathbf{r}}]_{\mathbf{i}\ell}^{\mathbf{m}} \varrho_{\mathbf{i}}(\mathbf{r}) \mathbf{Y}_{\ell}^{\mathbf{m}}(\theta,\varphi) \quad \forall \ \delta \leq \mathbf{r} \leq 1; \quad 0 \leq \theta \leq \pi; \quad 0 \leq \varphi \leq 2\pi,$$

- $\varrho_i$  : Legendre polynomial of order *i*
- N : Maximum degree of Legendre polynomial of order  $\varrho_i$
- $Y_{\ell}^m$  : Spherical Harmonic Basis
- $\ell_{max}$  : Maximum degree of  $Y_{\ell}^m$





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• System of Equation

$$\mathbf{AX}_{\mathbf{r}} = \mathbf{F}$$

#### where

•  $k(:= N(\ell^2 + m + 1) + i \in \{1, 2, ..., N(\ell_{max} + 1)^2\}), k' \text{ entry}$ 

$$\begin{aligned} [\mathbf{A}]_{\mathbf{k},\mathbf{k}'} &= \int_{\mathcal{D}} \tilde{\varepsilon}(\mathbf{x}) \nabla \left( \varrho_{i} \mathbf{Y}_{\ell}^{m} \right) \cdot \nabla \left( \varrho_{j} \mathbf{Y}_{\ell'}^{m'} \right) \\ &+ \int_{\mathcal{D}} \tilde{\lambda}(\mathbf{x}) \tilde{\mathcal{F}} \left( \overline{\tilde{\mathbf{w}}}(\mathbf{x}) \right) \varrho_{i} \mathbf{Y}_{\ell}^{m} \varrho_{j} \mathbf{Y}_{\ell'}^{m} \\ &+ \frac{\ell}{\delta} \int_{\partial \mathbf{B}_{\delta}(\mathbf{0})} \varrho_{i} \mathbf{Y}_{\ell}^{m} \varrho_{j} \mathbf{Y}_{\ell'}^{m'}, \end{aligned}$$

$$[\mathbf{F}]_{\mathbf{k}} = \int_{\mathcal{D}} \tilde{f}_{\boldsymbol{\ell} \mathbf{j}} \mathbf{Y}_{\boldsymbol{\ell}'}^{\mathbf{m}'} \quad \forall \ \mathbf{k} \in \{1, \dots, \mathsf{N}(\ell_{\mathsf{max}} + 1)^2\}.$$





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• HSP equation in unit ball <sup>1</sup>

$$\begin{aligned} -\Delta u_{\mathsf{e}} + \kappa^2 u_{\mathsf{e}}^2 &= 0 \quad \text{ in } B_1(\mathbf{0}), \\ u_{\mathsf{e}} &= \phi_{\mathsf{e}} \quad \text{ on } \mathbb{S}^2 \end{aligned}$$

•  $u_{\rm e}$  can be numerically approximated by  $\tilde{u}_{\rm e}$ 

$$\tilde{\mathbf{u}}_{\mathbf{e}}(\mathbf{r},\theta,\varphi) = \sum_{\ell=0}^{\ell_{\max}} \sum_{m=-\ell}^{\ell} \left[ \tilde{\phi}_{\mathbf{e}} \right]_{\ell}^{m} \frac{i_{\ell}(\mathbf{r})}{i_{\ell}(1)} \mathbf{Y}_{\ell}^{m}(\theta,\varphi)$$

for  $0 \le \mathbf{r} \le 1, \ 0 \le \theta \le \pi, \ 0 \le \varphi < 2\pi$ 







Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• HSP equation in unit ball <sup>1</sup>

$$\begin{aligned} -\Delta u_{\mathsf{e}} + \kappa^2 u_{\mathsf{e}}^2 &= 0 \quad \text{ in } B_1(\mathbf{0}), \\ u_{\mathsf{e}} &= \phi_{\mathsf{e}} \quad \text{ on } \mathbb{S}^2 \end{aligned}$$

•  $u_{\rm e}$  can be numerically approximated by  $\tilde{u}_{\rm e}$ 

$$\tilde{\mathbf{u}}_{\mathbf{e}}(\mathbf{r},\boldsymbol{\theta},\varphi) = \sum_{\ell=0}^{\boldsymbol{\ell}_{\max}} \sum_{m=-\ell}^{\boldsymbol{\ell}} \left[ \tilde{\phi}_{\mathbf{e}} \right]_{\ell}^{m} \frac{\mathbf{i}_{\ell}(\mathbf{r})}{\mathbf{i}_{\ell}(1)} \mathbf{Y}_{\ell}^{m}(\boldsymbol{\theta},\varphi)$$

for 
$$0 \le r \le 1, \ 0 \le \theta \le \pi, \ 0 \le \varphi < 2\pi$$
  
  $\circ \left[\tilde{\phi}_{\mathsf{e}}\right]_{\ell}^{m}$ : Numerical approximation of  $\left[\phi_{\mathsf{e}}\right]_{\ell}^{m_{2}}$ 

$$\left[\tilde{\phi}_{\mathsf{e}}\right]_{\ell}^{m} = \sum_{n=1}^{N_{\mathsf{leb}}} \omega_{\mathsf{n}}^{\mathsf{leb}} \phi_{\mathsf{e}}(\mathsf{s}_{\mathsf{n}}) \mathbf{Y}_{\ell}^{\mathsf{m}}(\mathsf{s}_{\mathsf{n}})$$

<sup>1</sup>Quan, Stamm, Maday: SISC, 41(2), B320-B350, 2019

<sup>2</sup>Lebedev: ZVMMF, 16(2), 293-306, 1976





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• Numerical Integration<sup>1,2</sup>

<sup>1</sup>Haxton: J.Phy.B, 40, 4443, 2007 <sup>2</sup>Parter: JSC, 14, 347-355, 1999





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• Numerical Integration<sup>1,2</sup>

$$\begin{split} \int_{\mathcal{D}} \mathbf{h}(\mathbf{x}) d\mathbf{x} &= \int_{\delta}^{1} r^{2} \int_{\mathbb{S}^{2}} \mathbf{h}(r, \mathbf{s}) d\mathbf{s} dr \\ &\approx \frac{1 - \delta}{2} \sum_{m=1}^{N_{\text{lgl}}} \sum_{n=1}^{N_{\text{leb}}} \omega_{m}^{\text{lgl}} \omega_{n}^{\text{leb}} \left( \frac{1 - \delta}{2} (\mathbf{x}_{m} + 1) + \delta \right)^{2} \\ &\times h \left( \frac{1 - \delta}{2} (\mathbf{x}_{m} + 1) + \delta, \mathbf{s}_{n} \right). \end{split}$$

<sup>1</sup>Haxton: J.Phy.B, 40, 4443, 2007 <sup>2</sup>Parter: JSC, 14, 347-355, 1999





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• Energy Computation<sup>1</sup>

$$\mathsf{E}_{\mathsf{s}} = \frac{\beta}{2} \int_{\Omega} \rho^{\mathsf{sol}}(\mathbf{x}) \psi_{\mathsf{r}}(\mathbf{x}) + \frac{\beta^2 \kappa^2 \varepsilon_{\mathsf{s}}}{8\pi} \int_{\Omega} \lambda(\mathbf{x}) \left(\psi_{\mathsf{r}}(\mathbf{x}) \sinh\left(\psi_{\mathsf{r}}(\mathbf{x})\right) - 2\cosh\left(\psi_{\mathsf{r}}(\mathbf{x})\right)\right)$$





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• Energy Computation<sup>1</sup>

$$E_{s} = \frac{\beta}{2} \int_{\Omega} \rho^{\text{sol}}(\mathbf{x}) \psi_{\mathsf{r}}(\mathbf{x}) + \frac{\beta^{2} \kappa^{2} \varepsilon_{\mathsf{s}}}{8\pi} \int_{\Omega} \lambda(\mathbf{x}) \left(\psi_{\mathsf{r}}(\mathbf{x}) \sinh\left(\psi_{\mathsf{r}}(\mathbf{x})\right) - 2\cosh\left(\psi_{\mathsf{r}}(\mathbf{x})\right)\right)$$

• Stopping Criteria

I

• Global Iterative Process

$$|E_s^k - E_s^{k-1}|/|E_s^k| \le \mathsf{tol}$$





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• Energy Computation<sup>1</sup>

$$\mathsf{E}_{\mathsf{s}} = \frac{\beta}{2} \int_{\Omega} \rho^{\mathsf{sol}}(\mathbf{x}) \psi_{\mathsf{r}}(\mathbf{x}) + \frac{\beta^2 \kappa^2 \varepsilon_{\mathsf{s}}}{8\pi} \int_{\Omega} \lambda(\mathbf{x}) \left(\psi_{\mathsf{r}}(\mathbf{x}) \sinh\left(\psi_{\mathsf{r}}(\mathbf{x})\right) - 2\cosh\left(\psi_{\mathsf{r}}(\mathbf{x})\right)\right)$$

- Stopping Criteria
  - Global Iterative Process

$$|E_s^k - E_s^{k-1}| / |E_s^k| \le \text{tol}$$

• DD loop

$$\frac{\|\mathbf{X}_{\mathsf{r}}^{\mathsf{k}} - \mathbf{X}_{\mathsf{r}}^{\mathsf{k}-1}\|_{\ell^2}}{\|\mathbf{X}_{\mathsf{r}}^{\mathsf{k}}\|_{\ell^2}} \le 10 \times \mathsf{tol}$$





Numerical Studies Conclusions and Outlook

• Energy Computation<sup>1</sup>

$$\mathsf{E}_{\mathsf{s}} = \frac{\beta}{2} \int_{\Omega} \rho^{\mathsf{sol}}(\mathbf{x}) \psi_{\mathsf{r}}(\mathbf{x}) + \frac{\beta^2 \kappa^2 \varepsilon_{\mathsf{s}}}{8\pi} \int_{\Omega} \lambda(\mathbf{x}) \left(\psi_{\mathsf{r}}(\mathbf{x}) \sinh\left(\psi_{\mathsf{r}}(\mathbf{x})\right) - 2\cosh\left(\psi_{\mathsf{r}}(\mathbf{x})\right)\right)$$

- Stopping Criteria
  - Global Iterative Process

$$|E_s^k - E_s^{k-1}| / |E_s^k| \le \mathsf{tol}$$

• DD loop

$$\frac{\|\boldsymbol{\mathsf{X}}_{\mathsf{r}}^{\mathsf{k}} - \boldsymbol{\mathsf{X}}_{\mathsf{r}}^{\mathsf{k}-1}\|_{\ell^2}}{\|\boldsymbol{\mathsf{X}}_{\mathsf{r}}^{\mathsf{k}}\|_{\ell^2}} \le 10 \times \mathsf{tol}$$

• Matrix loop

$$\frac{\|{\sf X}_{{\sf r},{\sf i}}^{\,\,{\sf k}}-{\sf X}_{{\sf r},{\sf i}}^{\,\,{\sf k}}-1}\|_{\ell^2}}{\|{\sf X}_{{\sf r},{\sf i}}^{\,\,{\sf k}}\|_{\ell^2}} \le 100\times{\sf tol}$$





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

• Constants in the model





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

- Constants in the model
  - ε<sub>s</sub>: 78.54
  - κ: 0.104 Å<sup>-1</sup>
  - ∘ *r<sub>p</sub>*: 1.4 Å
  - T: 298.15 K
  - tol:  $10^{-7}$





- Constants in the model
  - ε<sub>s</sub>: 78.54
  - κ: 0.104 Å<sup>-1</sup>
  - ∘ *r<sub>p</sub>*: 1.4 Å
  - T: 298.15 K
  - tol:  $10^{-7}$
  - Conversion to atomic units





### Potential for One Sphere

- Discretisation Parameters: N = 20,  $N_{lgl} = 200$
- Geometric Parameters:  $r_1 = 2$  Å,  $r_0 = 1$  Å, a = 0 Å







## Variation of $\psi_{r}$

Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

- Discretisation Parameters: N = 20,  $N_{lgl} = 200$
- Geometric Parameters:  $r_1 = 2$  Å,  $r_0 = 10$  Å, a = 0 Å



•  $\operatorname{Var}_{\psi}(r) := |\psi_{\operatorname{PB}}(r) - \psi_{\operatorname{LPB}}(r)|$ 





### Effect of Discretisation Parameters

- Discretisation Parameters: N = 30,  $N_{lgl} = 300$
- Geometric Parameters:  $r_1 = 2$  Å,  $r_0 = 5$  Å, a = 0 Å







## Effect of Discretisation Parameters

Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

- Discretisation Parameters: N = 30,  $N_{lgl} = 300$
- Geometric Parameters:  $r_1 = 2$  Å,  $r_0 = 5$  Å, a = 0 Å



• Similar observations for spherical discretisation





## Convergence of Global Strategy

- Caffeine Molecule
- Discretisation Parameters: N = 15,  $N_{lgl} = 50$ ,  $\ell_{max} = 9$ ,  $N_{leb} = 350$
- Geometric Parameters:  $r_0 = 5 \text{ Å}$ , a = 1 Å







- Hydrogen Fluoride Molecule
- Discretisation Parameters: N = 15,  $N_{lgl} = 50$ ,  $\ell_{max} = 8$ ,  $N_{leb} = 1202$
- Geometric Parameters:  $r_0 = 2 \text{ Å}$







## **Rotational Symmetry**

- Hydrogen Fluoride Molecule
- Discretisation Parameters: N = 15,  $N_{lgl} = 50$
- Geometric Parameters:  $r_0 = 2 \text{ Å}$ , a = 1 Å







## Visualisation of Potential

Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

- Visualisation of  $\psi_r$
- Discretisation Parameters: N = 15,  $N_{lgl} = 50$ ,  $\ell_{max} = 11$ ,  $N_{leb} = 1202$
- Geometric Parameters:  $r_0 = 1$  Å, a = 0.5 Å







## Effect of $\kappa$

- Hydrogen Fluoride Molecule
- Variation of  $\kappa$
- Discretisation Parameters: N = 15,  $N_{lgl} = 30$ ,  $\ell_{max} = 7$ ,  $N_{leb} = 86$
- Geometric Parameters:  $r_0 = 0$  Å, a = 0 Å







## **Conclusions and Outlook**

Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

#### Conclusions<sup>1</sup>

# • Formulation of domain decomposition method for PB equations

<sup>1</sup>J., Stamm, arXiv: 2309.06862, 2023

<sup>2</sup>Nottoli, Herbst, J., Lipparini, Mikhalev, Stamm, ddX: https://github.com/ddsolvation/ddX





## **Conclusions and Outlook**

Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

- Conclusions<sup>1</sup>
  - Formulation of domain decomposition method for PB equations
  - Development of a non-linear solver

<sup>2</sup>Nottoli, Herbst, J., Lipparini, Mikhalev, Stamm, ddX: https://github.com/ddsolvation/ddX





<sup>&</sup>lt;sup>1</sup>J., Stamm, arXiv: 2309.06862, 2023

Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

- Conclusions<sup>1</sup>
  - Formulation of domain decomposition method for PB equations
  - Development of a non-linear solver
  - Inclusion of Steric effects

<sup>1</sup> J., Stamm, arXiv: 2309.06862, 2023

<sup>2</sup>Nottoli, Herbst, J., Lipparini, Mikhalev, Stamm, ddX: https://github.com/ddsolvation/ddX





Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

- Conclusions<sup>1</sup>
  - Formulation of domain decomposition method for PB equations
  - Development of a non-linear solver
  - Inclusion of Steric effects
  - Current implementation for small molecules

<sup>1</sup>J., Stamm, arXiv: 2309.06862, 2023

<sup>2</sup>Nottoli, Herbst, J., Lipparini, Mikhalev, Stamm, ddX: https://github.com/ddsolvation/ddX


Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

- Conclusions<sup>1</sup>
  - Formulation of domain decomposition method for PB equations
  - Development of a non-linear solver
  - Inclusion of Steric effects
  - Current implementation for small molecules
- Outlook
  - Implementation to ddX library<sup>2</sup>

<sup>2</sup>Nottoli, Herbst, J., Lipparini, Mikhalev, Stamm, ddX: https://github.com/ddsolvation/ddX





29

<sup>&</sup>lt;sup>1</sup>J., Stamm, arXiv: 2309.06862, 2023

Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

- Conclusions<sup>1</sup>
  - Formulation of domain decomposition method for PB equations
  - Development of a non-linear solver
  - Inclusion of Steric effects
  - Current implementation for small molecules
- Outlook
  - Implementation to ddX library<sup>2</sup>
  - Acceleration techniques

<sup>2</sup>Nottoli, Herbst, J., Lipparini, Mikhalev, Stamm, ddX: https://github.com/ddsolvation/ddX





29

<sup>&</sup>lt;sup>1</sup> J., Stamm, arXiv: 2309.06862, 2023

Model Problem ddPB Method ddPB Derivation Numerical Studies Conclusions and Outlook

- Conclusions<sup>1</sup>
  - Formulation of domain decomposition method for PB equations
  - Development of a non-linear solver
  - Inclusion of Steric effects
  - Current implementation for small molecules
- Outlook
  - Implementation to ddX library<sup>2</sup>
  - Acceleration techniques



## Thank You!

<sup>1</sup>J., Stamm, arXiv: 2309.06862, 2023

<sup>2</sup>Nottoli, Herbst, J., Lipparini, Mikhalev, Stamm, ddX: https://github.com/ddsolvation/ddX





29